

On generalized solutions of some differential non-linear equations of order n

by J. LIĞEZA (Katowice)

Abstract. The paper contains some theorems on the existence and uniqueness of the solution of the equation

$$(*) \quad x^{(n)} = f_0(t, x, x', \dots, x^{(n-1)}) + \sum_{i=1}^m p_i(t) f_i(t, x, x', \dots, x^{(n-2)})$$

in the class of all distributions for which $(n-1)$ derivatives ($n \geq 2$) in the distribution sense are functions of finite variation in the interval (a, b) .

In $(*)$ the function $f_0(t, x_0, \dots, x_{n-1})$ is known and Lebesgue locally integrable in the set

$$D: a < t < b, \quad -\infty < x_0, \dots, x_{n-1} < \infty,$$

$p_i(t)$ for $i = 1, 2, \dots, m$ are given measures in (a, b) (see [1], [2]), and $f_i(t, x_0, \dots, x_{n-1})$ are continuous functions in D . The derivatives are understood in the distribution sense.

The principal results of this paper generalize some theorems for linear differential equations (see [6], [7], [8]).

In this note the sequential theory of distributions is used (see [5], [9]).

1. Let $p_r(t)$ for $r = 1, 2, \dots, m$ be given measures defined in an interval (a, b) , and $f_0(t, x_0, \dots, x_{n-1})$ a locally integrable function in the set

$$D: a < t < b, \quad -\infty < x_0, \dots, x_{n-1} < \infty.$$

Moreover, let $f_r(t, x_0, \dots, x_{n-2})$ be given continuous functions in D . We put

$$g(t, x, x', \dots, x^{(n-1)}) = f_0(t, x, x', \dots, x^{(n-1)}) + \sum_{r=1}^m p_r(t) f_r(t, x, x', \dots, x^{(n-2)})$$

for $n \geq 2$.

In this note the equation

$$(*) \quad x^{(n)} = g(t, x, x', \dots, x^{(n-1)})$$

will be examined, where the derivatives are understood in the distribution sense. We prove some theorems on the existence and uniqueness of solution of equation $(*)$ in the class of all distributions whose $(n-1)$

derivatives in the distribution sense are functions of finite variation in the interval (a, b) . This class will be denoted by $V_{(a,b)}^{(n-1)}$. The principal results of this paper generalize some results for linear differential equations (see [6], [7], [8]).

The sequential theory of the distributions (see [5], [9]) will be used. All distributions in this paper are real distributions. Moreover, all distributions of a single variable are defined in the interval (a, b) . The measurability and integrability of functions is understood in Lebesgue's sense.

2. DEFINITION 1. We say that a function $f(t, x_0, \dots, x_{n-1})$ defined in the set D satisfies condition C (*Carathéodory's condition*) if

1° for every fixed t , $f(t, x_0, \dots, x_{n-1})$ is continuous with respect to (x_0, \dots, x_{n-1}) ;

2° for fixed x_0, \dots, x_{n-1} , $f(t, x_0, \dots, x_{n-1})$ is measurable with respect to t .

DEFINITION 2. A sequence of smooth, non-negative and even functions $\{\delta_k(t)\}$ for which

$$1^\circ \int_{-\infty}^{\infty} \delta_k(t) dt = 1;$$

2° there is a sequence of positive numbers $\{a_k\}$ convergent to zero such that

$$\delta_k(t) = 0 \quad \text{for } |t| \geq a_k;$$

3° there are numbers M_0, M_1, \dots such that

$$a_k^s \int_{-\infty}^{\infty} |\delta_k^{(s)}(t)| dt < M_s,$$

holds for $k = 1, 2, \dots$ and every order s is called a *delta sequence* (see [4], [10]).

DEFINITION 3. We say that a distribution $f(t)$ is a *measure* if there exists a fundamental sequence $\{f_k(t)\}$ for f such that, for each compact interval $I \subset (a, b)$, the sequence of numbers $\{\int_I |f_k(t)| dt\}$ is bounded (see [1], [2]).

DEFINITION 4. Under a regular sequence $\{f_k(t)\}$ of a given distribution $f(t)$ we understand every sequence (see [10])

$$f_k(t) = (f * \delta_k)(t) = \int_{-\infty}^{\infty} f(t-s) \delta_k(s) ds.$$

DEFINITION 5. If for every regular sequence $\{f_k(t)\}$ of the distribution $f(t)$ the sequence $\{f_k(t_0)\}$ is convergent to some finite limit as $k \rightarrow \infty$, then the limit $\lim_{k \rightarrow \infty} f_k(t_0)$ is called the *mean value of the distribution* $f(t)$ in t_0 and denoted by $f(t_0)$ (see [4]).

The consistence of the definition follows from the fact that an interlaced sequence of two delta sequences is another delta sequence.

One may prove (see [4], [8]) the following

THEOREM 1. *If distribution $f(t)$ is a function of finite variation, then it has a mean value at every point $t_0 \in (a, b)$ and*

$$f(t_0) = \frac{1}{2}[f(t_0^+) + f(t_0^-)],$$

where $f(t_0^+)$ and $f(t_0^-)$ denote, respectively the right- and the left-hand side limits of the function $f(t)$ in t_0 .

3. Now we shall prove the principal results. At first we assume the following hypotheses:

HYPOTHESIS H_1 .

1° The function $f_0(t, x_0, \dots, x_{n-1})$ satisfies condition C.

2° The functions $f_r(t, x_0, \dots, x_{n-2})$ are continuous in D with respect to (t, x_0, \dots, x_{n-2}) .

3° $|f_0(t, x_0, \dots, x_{n-1})| \leq \sum_{i=0}^{n-1} q_{0i}(t)|x_i| + q_{0n}(t)$, where $q_{0i}(t)$ are non-negative, locally integrable functions in (a, b) for $i = 0, 1, \dots, n$.

4° $|f_r(t, x_0, \dots, x_{n-2})| \leq \sum_{i=0}^{n-2} q_{ri}(t)|x_i| + q_{rn-1}(t)$, where $q_{ri}(t)$ are non-negative and continuous functions in (a, b) for $i = 0, 1, \dots, n-1$ and $r = 1, 2, \dots, m$.

HYPOTHESIS H_2 .

1° Assumptions H_1 : 1°, 3°, 4° are fulfilled.

2° The functions $f_r(t, x_0, \dots, x_{n-2})$ have continuous partial derivatives of the first order in D with respect to (t, x_0, \dots, x_{n-2}) for $r = 1, 2, \dots, m$.

HYPOTHESIS H_3 .

1° Assumptions H_1 : 1°, H_2 : 2° are satisfied.

2° $|f_0(t, x_0, \dots, x_{n-1}) - f_0(t, \bar{x}_0, \dots, \bar{x}_{n-1})| \leq \sum_{i=0}^{n-1} q_{0i}(t)|x_i - \bar{x}_i|$, where $q_{0i}(t)$ are non-negative, locally integrable functions in (a, b) for $i = 0, 1, \dots, n-1$.

3° $|f_r(t, x_0, \dots, x_{n-2}) - f_r(t, \bar{x}_0, \dots, \bar{x}_{n-2})| \leq \sum_{i=0}^{n-2} q_{ri}(t)|x_i - \bar{x}_i|$, where $q_{ri}(t)$ are non-negative and continuous functions in (a, b) for $i = 0, 1, \dots, n-2$ and $r = 1, 2, \dots, m$.

4° $|f_0(t, 0, \dots, 0)| \leq u(t)$, where $u(t)$ is a locally integrable function in (a, b) .

We put

$$W_{n-1}(t) = \sum_{\mu=0}^{n-1} \frac{x_{\mu}(t-t_0)^{\mu}}{\mu!}$$

for arbitrary $\kappa_\mu \in E^1$ and $t_0 \in (a, b)$,

$$g_k(t, x, x', \dots, x^{(n-1)}) \\ = f_0(t, x, x', \dots, x^{(n-1)}) + \sum_{r=1}^m p_{rk}(t) f_r(t, x, x', \dots, x^{(n-2)}),$$

where

$$p_{rk}(t) = (p_r * \delta_k)(t) \quad \text{for } k = 1, 2, \dots$$

THEOREM 2. *Let Hypothesis H₂ be fulfilled. Then the problem*

$$(**) \quad \begin{aligned} x^{(n)} &= g(t, x, x', \dots, x^{(n-1)}), \\ x^{(d)}(t_0) &= \kappa_d, \quad t_0 \in (a, b), \quad d = 0, 1, \dots, n-1 \end{aligned}$$

has at least one solution in the class $V_{(a,b)}^{(n-1)}$.

Proof. Let $x_k(t)$ be a solution of the equation

$$(2.0) \quad x(t) = \int_{t_0}^t \frac{(t-s)^{n-1}}{(n-1)!} g_k(s, x(s), x'(s), \dots, x^{(n-1)}(s)) ds + W_{n-1}(t).$$

Then

$$(2.1) \quad |Y_k(t)| \leq \left[|Y_k(t_0)| + \left| \int_{t_0}^t |B_k(s)| ds \right| \right] \exp \left| \int_{t_0}^t \|A_k(s)\| ds \right|,$$

where

$$|Y_k(t)| = \sum_{d=0}^{n-1} |x_k^{(d)}(t)|, \quad |B_k(t)| = q_{0n}(t) + \sum_{r=1}^m |p_{rk}(t)| q_{rn-1}(t)$$

and

$$\|A_k(t)\| = (n-1) + q_{0n-1}(t) + \sum_{i=0}^{n-2} (q_{0i}(t) + \sum_{r=1}^m |p_{rk}(t)| q_{ri}(t)).$$

Thus the sequences $\{x_k^{(d)}\}$ are locally equibounded in (a, b) for sufficiently large k and $d = 0, 1, \dots, n-1$. Let I be an arbitrary compact interval such that $I \subset (a, b)$ and $x_0 \in I$. From Helly's theorem it follows that a subsequence $\{x_{v_k}^{(d)}\}$ of $\{x_k^{(d)}\}$ is convergent to a function of finite variation in I for $d = 0, 1, \dots, n-1$, respectively. Hence we infer (see [8]) that there exists a subsequence $\{x_{u_k}^{(d)}\}$ of $\{x_k^{(d)}\}$ distributionally convergent to a function $x^{(d)}$ of finite variation in (a, b) . In view of [1] and [3] (p. 642) we conclude that there exists a distributional limit

$$\lim_{u \rightarrow \infty} (d) g_{u_k}(t, x_{u_k}(t), x'_{u_k}(t), \dots, x_{u_k}^{(n-1)}(t)) = g(t, x(t), x'(t), \dots, x^{(n-1)}(t)).$$

Hence the function $x(t)$ is a solution of equation (*).

We shall prove that $x^{(d)}(t_0) = \kappa_d$. In fact, from the almost uniform convergence of the sequences $\{x_{u_k}^{(d)}\}$ for $\lambda = 0, 1, \dots, n-2$ we have

$x^{(\lambda)}(t_0) = \kappa_\lambda$. Moreover, by (2.0), Hypothesis H_2 , we obtain

$$(2.2) \quad \begin{aligned} x_{u_k}^{(n-1)}(t) &= \int_{t_0}^t g_{u_k}(s, x_{u_k}(s), x'_{u_k}(s), \dots, x_{u_k}^{(n-1)}(s)) ds + \kappa_{n-1} \\ &= \int_{t_0}^t f_0(s, x_{u_k}(s), x'_{u_k}(s), \dots, x_{u_k}^{(n-1)}(s)) ds + \\ &\quad + \left[\sum_{r=1}^m P_{ru_k}(s) g_{ru_k}(s) \right] \Big|_{t_0}^t - \int_{t_0}^t \left[\sum_{r=1}^m P_{ru_k}(s) \cdot \frac{dg_{ru_k}}{ds} \right] ds + \kappa_{n-1}, \end{aligned}$$

where

$$\begin{aligned} P'_r &= p_r, \quad P_{ru_k}(t) = (P_r * \delta_{u_k})(t) \\ \text{and} \quad g_{ru_k}(t) &= f_r(t, x_{u_k}(t), x'_{u_k}(t), \dots, x_{u_k}^{(n-2)}(t)). \end{aligned}$$

From (2.2), Definition 5, Theorem 1 and [3] (p. 642) we infer that $x^{(n-1)}(t_0) = \kappa_{n-1}$. This ends the proof of Theorem 2.

Similarly one may prove the following

THEOREM 3. *Let Hypothesis H_1 be fulfilled. Then equation (*) has at least one solution in the class $V_{(a,b)}^{(n-1)}$.*

THEOREM 4. *Let Hypothesis H_3 be fulfilled. Then problem (**) has exactly one solution in the class $V_{(a,b)}^{(n-1)}$.*

Proof. Suppose that \tilde{x}_1 and \tilde{x}_2 are solutions of problem (**) such that $\tilde{x}_1 \neq \tilde{x}_2$ and $\tilde{x}_1, \tilde{x}_2 \in V_{(a,b)}^{(n-1)}$. We denote by $\{\tilde{x}_{1k}\}, \{\tilde{x}_{2k}\}$ arbitrary regular sequences of \tilde{x}_1 and \tilde{x}_2 respectively. We consider the sequences $\{Y_{ik}^{(d)}\}$ defined as follows:

$$(4.0) \quad Y_{ik}^{(d)}(t) = \left[\int_{t_0}^t \frac{(t-s)^{n-1}}{(n-1)!} g_k(s, \tilde{x}_{ik}(s), \tilde{x}'_{ik}(s), \dots, \tilde{x}_{ik}^{(n-1)}(s)) ds + W_{n-1}(t) \right]^{(d)}$$

for $d = 0, 1, \dots, n-1$ and $i = 1, 2$.

From Helly's theorem it follows that a subsequence $\{Y_{iu_k}^{(d)}\}$ of $\{Y_{ik}^{(d)}\}$ is convergent to a function $Y_i^{(d)}$ of finite variation in (a, b) for $i = 1, 2$, $d = 0, 1, \dots, n-1$ and $u \rightarrow \infty$. Moreover, $Y_i^{(d)}(t_0) = \kappa_d$. Hence by (4.0) we get

$$(4.1) \quad Y_i(t) = \tilde{x}_i(t) \quad \text{for } i = 1, 2.$$

We put

$$(4.2) \quad Z_{u_k}(t) = Y_{1u_k}(t) - Y_{2u_k}(t), \quad B_{du_k}(t) = \left| |\tilde{x}_{1u_k}^{(d)}(t) - \tilde{x}_{2u_k}^{(d)}(t)| - |Z_{u_k}^{(d)}(t)| \right|.$$

In view of (4.0), (4.1), (4.2) and Hypothesis H_3 we have

$$(4.3) \quad |\bar{Y}_{u_k}(t)| \leq \left| \int_{t_0}^t |\bar{B}_{u_k}(s)| ds \right| \exp \left| \int_{t_0}^t \|A_{u_k}(s)\| ds \right|,$$

where

$$|\bar{Y}_{u_k}(t)| = \sum_{d=0}^{n-1} |Z_{u_k}^{(d)}(t)|,$$

$$|\bar{B}_{u_k}(t)| = \sum_{i=0}^{n-2} \left(\sum_{r=1}^m |p_{ru_k}(t)| q_{ri}(t) \right) E_{iu_k}(t) + \sum_{i=0}^{n-1} q_{0i}(t) E_{iu_k}(t).$$

Hence $\lim_{u \rightarrow \infty} (d)Z_{u_k} = 0$. By Theorem 3 and (4.1) the proof of our assertion is ended.

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