

Extrapolation methods to solve non-autonomous retarded partial differential equations

by

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Abstract. Using extrapolation spaces introduced by Da Prato–Grisvard and Nagel we prove a non-autonomous perturbation theorem for Hille–Yosida operators. The abstract result is applied to non-autonomous retarded partial differential equations.

1. Introduction. The purpose of this note is to study non-autonomous perturbations of (not necessarily densely defined) Hille–Yosida operators. The abstract result of this paper will be illustrated by means of non-autonomous retarded partial differential equations.

Let X be a Banach space and A a linear operator on X with domain $D(A)$. We say that $(A, D(A))$ is a *Hille–Yosida* operator if there exists $\omega \in \mathbb{R}$ such that every $\lambda > \omega$ is in the resolvent set $\rho(A)$ of A and

$$\sup\{\|(\lambda - \omega)^n(\lambda - A)^{-n}\| : \lambda \geq \omega, n \in \mathbb{N}\} < \infty.$$

If the constant ω can be chosen negative, then A is called of *negative type*.

It follows from the Hille–Yosida theorem that a Hille–Yosida operator generates a C_0 -semigroup on the closure of its domain. More precisely, we have (cf. [Hi-Ph], Thm. 12.2.4).

PROPOSITION 1.1 *Let $(A, D(A))$ be a Hille–Yosida operator on the Banach space X . Then the part $(A_0, D(A_0))$ of A in $X_0 := (\overline{D(A)}, \|\cdot\|)$ given by*

$$D(A_0) := \{x \in D(A) : Ax \in X_0\}, \quad A_0x := Ax \quad \text{for } x \in D(A_0),$$

generates a C_0 -semigroup $(T_0(t))_{t \geq 0}$ on X_0 . Moreover, $\rho(A) \subset \rho(A_0)$ and $(\lambda - A_0)^{-1}$ is the restriction of $(\lambda - A)^{-1}$ to X_0 for $\lambda \in \rho(A)$.

For the rest of this paper we assume without loss of generality that $(A, D(A))$ is a Hille–Yosida operator of negative type on X .

Now we summarize some basic facts on extrapolation spaces and Favard classes, which will be used throughout this paper. For more details we refer to [Na1], [Wa] and [Na-Si] where also the missing proofs can be found.

On the space X_0 we introduce a new norm by

$$\|x\|_{-1} := \|A_0^{-1}x\|, \quad x \in X_0.$$

The completion of $(X_0, \|\cdot\|_{-1})$ will be called the *extrapolation space* of X_0 associated with A_0 and it will be denoted by X_{-1} .

Since $A_0^{-1}T_0(t) = T_0(t)A_0^{-1}$ for all $t \geq 0$, one has

$$\|T_0(t)x\|_{-1} \leq \|T_0(t)\|_{\mathcal{L}(X)}\|x\|_{-1} \quad \text{for } x \in X_0 \text{ and } t \geq 0.$$

This shows that the operator $T_0(t)$ can be uniquely extended to a bounded operator on the Banach space X_{-1} . The result is a C_0 -semigroup on X_{-1} denoted by $(T_{-1}(t))_{t \geq 0}$. The semigroup $(T_{-1}(t))_{t \geq 0}$ will be called the *extrapolated semigroup* of $(T_0(t))_{t \geq 0}$. If we denote by $A_{-1} : D(A_{-1}) \rightarrow X_{-1}$ the generator of $(T_{-1}(t))_{t \geq 0}$, then we have the following properties (see [Na-Si], Prop. 1.3 and Thm. 1.4).

- (i) $\|T_{-1}(t)\|_{\mathcal{L}(X_{-1})} = \|T_0(t)\|_{\mathcal{L}(X_0)}$.
- (ii) $D(A_{-1}) = X_0$.
- (iii) $A_{-1} : X_0 \rightarrow X_{-1}$ is the unique extension of $A_0 : X_0 \supset D(A_0) \rightarrow X_{-1}$ to an isometry $X_0 \rightarrow X_{-1}$.
- (iv) A_{-1} is invertible with $(A_{-1})^{-1} \in \mathcal{L}(X_{-1})$.

The original space X now fits into this scheme of spaces X_0 and X_{-1} (see [Na-Si], Thm. 1.7).

THEOREM 1.2. *Let $(A, D(A))$ be a Hille–Yosida operator of negative type on the Banach space X . Then $X_0 := \overline{D(A)}$ is dense in X with respect to the norm*

$$\|x\|_{-1} := \|A^{-1}x\|, \quad x \in X.$$

Hence, the extrapolation space X_{-1} is also the completion of $(X, \|\cdot\|_{-1})$ and therefore $X \hookrightarrow X_{-1}$. Moreover, the operator A_{-1} is an extension of A , hence $(A_{-1})^{-1}X = D(A)$.

Let us also recall the definition of the Favard class of a C_0 -semigroup (cf. [Bu-Be], Chap. 3). The *Favard class* of the generator A_0 is the space

$$F(A_0) := \left\{ x \in X_0 : \limsup_{t \rightarrow 0} \frac{1}{t} \|T_0(t)x - x\| < \infty \right\}$$

equipped with the norm

$$\|x\|_{F(A_0)} := \limsup_{t \rightarrow 0} \frac{1}{t} \|T_0(t)x - x\| \quad \text{for } x \in F(A_0).$$

It is easy to see that $F(A_0)$ is invariant under $(T_0(t))$ and $D(A_0) \subset F(A_0)$. Similarly we have $X_0 \subset F(A_{-1})$. In [Na-Si], Prop. 3.2, it is shown that $F(A_{-1})$ is the extrapolation space of $F(A_0)$.

PROPOSITION 1.3. *For the Favard classes $F(A_0)$ and $F(A_{-1})$ the following holds.*

- (i) $A_{-1}F(A_0) = F(A_{-1})$.
- (ii) $\|A_{-1}x\|_{F(A_{-1})} = \|x\|_{F(A_0)}$ for $x \in F(A_0)$.
- (iii) $D(A_0) \subseteq D(A) \hookrightarrow F(A_0) \hookrightarrow X_0 \subseteq X \hookrightarrow F(A_{-1}) \hookrightarrow X_{-1}$.
- (iv) $T_{-1}(t)F(A_{-1}) \subseteq F(A_{-1})$.

Let now $C : X_0 \rightarrow F(A_{-1})$ be a bounded operator. Then it is proved in a recent paper [Ni-Rh] that the operator

$$D(B_0) := \{x \in X_0 : A_{-1}x + Cx \in X_0\}, \quad B_0x := A_{-1}x + Cx, \quad x \in D(B_0),$$

generates a C_0 -semigroup $(S_0(t))_{t \geq 0}$ on X_0 . This semigroup is given by the variation of constants formula

$$(1) \quad S_0(t)x = T_0(t)x + \int_0^t T_{-1}(t-s)CS_0(s)x ds, \quad x \in X_0, t \geq 0.$$

In this paper we shall generalize this result to the case of time depending perturbations. We prove that if $C(\cdot)$ is a strongly continuous function from $[0, T]$ into the space of bounded linear operators $\mathcal{L}(X_0, F(A_{-1}))$, then the variation of constants formula

$$(2) \quad U(t, s)x = T_0(t-s)x + \int_s^t T_{-1}(t-\sigma)C(\sigma)U(\sigma, s) d\sigma,$$

$$x \in X_0, 0 \leq s < t \leq T,$$

gives a strongly continuous evolution family on X_0 .

As an application we prove in Section 3 that the variation of constants formula (2) solves the non-autonomous retarded partial differential equation

$$(NRDE) \quad \begin{cases} x'(t) = Bx(t) + L(t)x_t \\ x(\tau) = f(\tau - s), \quad s - r \leq \tau \leq s, 0 \leq s < t \leq T, \end{cases}$$

on $C([-r, 0], E)$, where E is any Banach space, B generates a C_0 -semigroup on E and $L(\cdot)$ is a strongly continuous operator-valued function from $[0, T]$ into $\mathcal{L}(C([-r, 0], E), E)$. We mention here that Clément *et al.* (see [Cl], [Cl1] and [Cl2]) proved a similar variation of constants formula by using duality methods in the sum-reflexive case. The non-autonomous retarded partial differential equation (NRDE) can also be solved by using the theory of multiplicative perturbations (see [De-Sch-Zh]).

Abstract extrapolation spaces have been introduced by Da Prato–Grisvard [DaP-Gr] and Nagel [Na1] and used for various purposes (cf. [Am], [vNe], [Na-Si] and [Ni-Rh]).

Concerning evolution families and their connection with non-autonomous Cauchy problems we refer to [Pa] and [Ta]. For terminology and basic re-

sults on semigroup theory we follow [Go], [Na] and [Pa] and for retarded differential equations we refer to [Ha] and [Di-vGi-Lu-Wa].

2. Non-autonomous perturbation of Hille–Yosida operators. The aim of this section is to prove that the variation of constants formula (2) defines an evolution family.

DEFINITION 2.1. Let $T > 0$ and $\Delta := \{(t, s) \in \mathbb{R}^2 : 0 \leq s \leq t \leq T\}$. A family $(U(t, s))_{(t,s) \in \Delta}$ of bounded linear operators on a Banach space X is called an *evolution family* on X if the following conditions are satisfied.

- (a) $U(t, t) = I$ and $U(t, r)U(r, s) = U(t, s)$ for $0 \leq s \leq r \leq t \leq T$,
- (b) $\Delta \ni (t, s) \mapsto U(t, s)x$ is continuous for each $x \in X$.

Throughout this section we consider a Hille–Yosida operator $(A, D(A))$ of negative type and as in the previous section we consider the scale of spaces $D(A_0) \subseteq D(A) \hookrightarrow F(A_0) \hookrightarrow X_0 \subseteq X \hookrightarrow F(A_{-1}) \hookrightarrow X_{-1}$ and the C_0 -semigroups $(T_0(t))_{t \geq 0}$ and $(T_{-1}(t))_{t \geq 0}$. Moreover, let $C(\cdot) \in C([0, T], \mathcal{L}_s(X_0, F(A_{-1})))$ be the Banach space of all strongly continuous functions $F(\cdot) : [0, T] \rightarrow \mathcal{L}(X_0, F(A_{-1}))$.

In order to prove the main result of this section, we will need the following lemma due to Nagel and Sinestrari (see [Na-Si], Prop. 3.1).

LEMMA 2.2. For $f \in L^1(\mathbb{R}_+, F(A_{-1}))$ and $t \geq 0$ we define

$$(T_{-1} * f)(t) := \int_0^t T_{-1}(t-s)f(s) ds.$$

For this convolution integral the following properties hold with a constant $M_1 < \infty$ independent of f and t :

- (i) $(T_{-1} * f)(t) \in X_0$.
- (ii) $\|(T_{-1} * f)(t)\| \leq M_1 \|f\|_{L^1((0,t), F(A_{-1}))}$.
- (iii) $\lim_{t \searrow 0} \|(T_{-1} * f)(t)\| = 0$.

From Lemma 2.2 follows by successive approximation the existence and uniqueness of the evolution family $(U(t, s))_{(t,s) \in \Delta}$ satisfying (2).

THEOREM 2.3. Let $(A, D(A))$ be a Hille–Yosida operator of negative type on the Banach space X and consider $X_0 := \overline{D(A)}$. Moreover, let $C(\cdot) \in C([0, T], \mathcal{L}_s(X_0, F(A_{-1})))$. The expansion

$$(3) \quad U(t, s) = \sum_{n=0}^{\infty} U_n(t, s), \quad \text{where}$$

$$(4) \quad U_0(t, s) := T_0(t-s) \text{ and } U_{n+1}(t, s) := \int_s^t T_{-1}(t-\sigma)C(\sigma)U_n(\sigma, s) d\sigma,$$

converges in the uniform operator topology of $\mathcal{L}(X_0)$ uniformly on Δ and defines an evolution family $(U(t, s))_{(t,s) \in \Delta}$ on X_0 , satisfying

$$(5) \quad \|U(t, s)\| \leq M e^{Mv(t,s)(t-s)} \quad \text{for } (t, s) \in \Delta,$$

where M is a constant and $v(t, s) := \sup_{s \leq \sigma \leq t} \|C(\sigma)\|_{\mathcal{L}(X_0, F(A_{-1}))}$. In addition, the variation of constants formula (2) holds.

Proof. One can see by Lemma 2.2(i), (iii), that for each $n \in \mathbb{N}$, $U_n(t, s)X_0 \subset X_0$ for all $(t, s) \in \Delta$ and $\Delta \ni (t, s) \mapsto U_n(t, s)$ is strongly continuous on X_0 , where $(U_n(t, s))_{(t,s) \in \Delta}$ is the family of operators given by (4). From Lemma 2.2(ii) it follows that

$$\begin{aligned} \|U_1(t, s)x\| &= \left\| \int_0^{t-s} T_{-1}(t-s-\sigma)C(\sigma+s)T_0(\sigma)x d\sigma \right\| \\ &\leq M \int_0^{t-s} \|C(\sigma+s)T_0(\sigma)x\|_{F(A_{-1})} d\sigma \leq M^2 v(t, s)(t-s)\|x\|, \end{aligned}$$

where $v(t, s) := \sup_{s \leq \sigma \leq t} \|C(\sigma)\|_{\mathcal{L}(X_0, F(A_{-1}))}$, $x \in X_0$ and $(t, s) \in \Delta$. By induction we obtain

$$\|U_n(t, s)\| \leq M^{n+1} v(t, s)^n \frac{(t-s)^n}{n!}, \quad (t, s) \in \Delta, n \in \mathbb{N}.$$

This implies that the expansion

$$U(t, s) = \sum_{n=0}^{\infty} U_n(t, s)$$

converges in the uniform operator topology of $\mathcal{L}(X_0)$ uniformly on Δ and defines a strongly continuous family $(U(t, s))_{(t,s) \in \Delta}$ on X_0 , since $\Delta \ni (t, s) \mapsto U_n(t, s)$ is strongly continuous on X_0 for each $n \in \mathbb{N}$. Moreover, the estimate (5) holds. From (3) and (4) it is easy to see that the family $(U(t, s))_{(t,s) \in \Delta}$ satisfies the variation of constants formula (2) and therefore $U(t, t) = I$ for all $t \in [0, T]$.

It now remains to show that

$$U(t, r)U(r, s) = U(t, s) \quad \text{for } 0 \leq s \leq r \leq t \leq T.$$

Since

$$U(t, r)U(r, s) = \sum_{n=0}^{\infty} U_n(t, r) \sum_{m=0}^{\infty} U_m(r, s) = \sum_{n=0}^{\infty} \sum_{j=0}^n U_{n-j}(t, r)U_j(r, s),$$

we only have to prove that

$$\sum_{j=0}^n U_{n-j}(t, r)U_j(r, s) = U_n(t, s) \quad \text{for } 0 \leq s \leq r \leq t \leq T.$$

The assertion is true for $n = 0$ and by induction we have

$$\begin{aligned} \sum_{j=0}^{n+1} U_{n+1-j}(t, r)U_j(r, s) &= \sum_{j=0}^n U_{n+1-j}(t, r)U_j(r, s) + T_0(t-r)U_{n+1}(r, s) \\ &= \sum_{j=0}^n \int_r^t T_{-1}(t-\sigma)C(\sigma)U_{n-j}(\sigma, r)U_j(r, s) d\sigma \\ &\quad + \int_r^t T_{-1}(t-\sigma)C(\sigma)U_n(\sigma, s) d\sigma \\ &= \left(\int_r^t + \int_s^r \right) T_{-1}(t-\sigma)C(\sigma)U_n(\sigma, s) d\sigma \\ &= \int_s^t T_{-1}(t-\sigma)C(\sigma)U_n(\sigma, s) d\sigma \\ &= U_{n+1}(t, s) \quad \text{for } 0 \leq s \leq r \leq t \leq T. \blacksquare \end{aligned}$$

Remark 2.4. If in Theorem 2.3, $(A, D(A))$ is an arbitrary Hille–Yosida operator on X , then it is easy to see, using the rescaling procedure (cf. [Na], A-I, 3.1), that all assertions of Theorem 2.3 are true except the estimate (5) which is replaced by

$$(6) \quad \|U(t, s)\| \leq Me^{(\omega + Mv(t,s))(t-s)} \quad \text{for } (t, s) \in \Delta,$$

where M and ω are such that $\|T_0(t)\| \leq Me^{\omega t}$ for $t \geq 0$.

Let $A(t)$ be the part of $A_{-1} + C(t)$ in X_0 , i.e.

$$\begin{aligned} D(A(t)) &:= \{x \in X_0 : A_{-1}x + C(t)x \in X_0\} \\ A(t)x &:= A_{-1}x + C(t)x, \quad x \in D(A(t)), \quad t \in [0, T]. \end{aligned}$$

As in [Cl2], Lemma 2.4, one can see that if $x \in D(A(t))$ for all $t \in [0, T]$, then

$$(7) \quad \lim_{\substack{s, r \rightarrow t \\ r < s}} \frac{1}{s-r} (U(s, r)x - x) = A(t)x.$$

In fact, let $t \in [0, T]$ and $x \in D(A(t))$. Then from Lemma 2.2 we have

$$\begin{aligned} \frac{1}{s-r} \left\| \int_0^{s-r} T_{-1}(s-r-\sigma)[C(\sigma+r)U(\sigma+r, r)x - C(t)x] d\sigma \right\| \\ \leq \frac{M}{s-r} \int_0^{s-r} \|C(\sigma+r)U(\sigma+r, r)x - C(t)x\|_{F(A_{-1})} d\sigma. \end{aligned}$$

Since $C(\cdot) \in C([0, T], \mathcal{L}_s(X_0, F(A_{-1})))$, we obtain

$$\lim_{\substack{s, r \rightarrow t \\ r < s}} \frac{1}{s-r} \left\| \int_0^{s-r} T_{-1}(s-r-\sigma)[C(\sigma+r)U(\sigma+r, r)x - C(t)x] d\sigma \right\| = 0.$$

So by (2) follows

$$\begin{aligned} 0 &= \lim_{\substack{s, r \rightarrow t \\ r < s}} \frac{1}{s-r} \left[(U(s, r)x - x) - (T_0(s-r)x - x) - \int_r^s T_{-1}(s-\sigma)C(t)x d\sigma \right] \\ &= \lim_{\substack{s, r \rightarrow t \\ r < s}} \frac{1}{s-r} \left[(U(s, r)x - x) - \int_0^{s-r} T_{-1}(s-r-\sigma)(A_{-1}x + C(t)x) d\sigma \right]. \end{aligned}$$

From $A_{-1}x + C(t)x \in X_0$ the assertion follows.

Since (7) holds and with the same proof as in Theorem 2.5 of [Cl2] we obtain the following relation between $A(\cdot)$ and the evolution family $(U(t, s))_{(t,s) \in \Delta}$ given by Theorem 2.3.

COROLLARY 2.5. *Let the assumptions be as in Theorem 2.3. Let $s \in [0, T]$ and $x \in D(A(s))$. Then the evolution family $(U(t, s))_{(t,s) \in \Delta}$ satisfies*

$$\begin{aligned} (a) \quad \frac{\partial^+}{\partial t} U(t, s)x \Big|_{t=s} &= A(s)x, \\ (b) \quad \frac{\partial}{\partial s} U(t, s)x &= -U(t, s)A(s)x, \end{aligned}$$

where the right derivative in (a) and the derivative in (b) are in the norm topology of X_0 .

3. Non-autonomous retarded partial differential equations. In

this section we consider a C_0 -semigroup $(S(t))_{t \geq 0}$ on a Banach space E with generator $(B, D(B))$. Denote by $C_E := C([-r, 0], E)$ the Banach space of all continuous functions from $[-r, 0]$ into E , where r is a positive constant. Let $L(\cdot) \in C([0, T], \mathcal{L}_s(C_E, E))$.

Using extrapolation methods and especially the variation of constants formula (2), we solve the following non-autonomous retarded partial differential equation:

$$(NRDE) \quad \begin{cases} x'(t) = Bx(t) + L(t)x_t \\ x(\tau) = f(\tau - s), \quad s - r \leq \tau \leq s, \quad 0 \leq s < t \leq T, \end{cases}$$

on C_E , where f is a given function in C_E and $x_t \in C_E$ denotes the function

$$x_t(\tau) := x(t + \tau) \quad \text{for } \tau \in [-r, 0].$$

We consider the Banach space $X := E \times C_E$ equipped with the norm

$$\left\| \begin{pmatrix} \eta \\ g \end{pmatrix} \right\| := \|\eta\|_E + \|g\|_{C_E} = \|\eta\|_E + \sup_{-r \leq \tau \leq 0} \|g(\tau)\|_E \quad \text{for } \begin{pmatrix} \eta \\ g \end{pmatrix} \in X.$$

Let $M \geq 1$, $\omega \geq 0$ be two constants such that

$$\|S(t)\| \leq M e^{\omega t} \quad \text{for } t \geq 0.$$

We denote by δ_0 the Dirac measure concentrated at zero and $\delta'_0 f := f'(0)$ for $f \in C_E^1 := \{f \in C_E : f \text{ is differentiable and } f' \in C_E\}$.

The following lemma will be used to prove well-posedness of the Cauchy problem (NRDE).

LEMMA 3.1. *With the notations introduced above, the matrix operator*

$$\mathcal{A} := \begin{pmatrix} 0 & B\delta_0 - \delta'_0 \\ 0 & d/d\tau \end{pmatrix} \quad \text{with } D(\mathcal{A}) := \{0\} \times \{f \in C_E^1 : f(0) \in D(B)\}$$

on X satisfies

$$(\omega, \infty) \subset \rho(\mathcal{A}) \quad \text{and} \quad \|(\lambda - \mathcal{A})^{-n}\| \leq \frac{M}{(\lambda - \omega)^n}$$

for all $\lambda > \omega$ and $n \in \mathbb{N}$. This means that \mathcal{A} is a Hille–Yosida operator on X .

Proof. For $\lambda > \omega$, $\begin{pmatrix} \eta \\ g \end{pmatrix} \in X$ and $\begin{pmatrix} 0 \\ f \end{pmatrix} \in D(\mathcal{A})$ we have

$$\begin{pmatrix} \eta \\ g \end{pmatrix} = (\lambda - \mathcal{A}) \begin{pmatrix} 0 \\ f \end{pmatrix} = \begin{pmatrix} f'(0) - Bf(0) \\ (\lambda - d/d\tau)f \end{pmatrix}.$$

Hence,

$$(8) \quad \begin{cases} f(\tau) = e^{\lambda\tau} f(0) + \int_{\tau}^0 e^{\lambda(\tau-\sigma)} g(\sigma) d\sigma, \\ f'(0) - Bf(0) = \eta, \end{cases}$$

for $\tau \in [-r, 0]$. Since $(\omega, \infty) \subset \rho(B)$, it follows from (8) that

$$(9) \quad f(\tau) = e^{\lambda\tau} (\lambda - B)^{-1} (g(0) + \eta) + \int_{\tau}^0 e^{\lambda(\tau-\sigma)} g(\sigma) d\sigma \quad \text{for } \tau \in [-r, 0].$$

This implies $(\omega, \infty) \subset \rho(\mathcal{A})$ and

$$(\lambda - \mathcal{A})^{-1} \begin{pmatrix} \eta \\ g \end{pmatrix} = \begin{pmatrix} 0 \\ f \end{pmatrix},$$

where f is given by (9). One can show by induction that for $n \in \mathbb{N}$,

$$(\lambda - \mathcal{A})^{-n} \begin{pmatrix} \eta \\ g \end{pmatrix} = \begin{pmatrix} 0 \\ f_n \end{pmatrix},$$

where

$$f_n(\tau) = \sum_{p=0}^{n-1} e^{\lambda\tau} \frac{(-\tau)^p}{p!} (\lambda - B)^{-(n-p)} (g(0) + \eta) + \frac{1}{(n-1)!} \int_{\tau}^0 (\sigma - \tau)^{n-1} e^{\lambda(\tau-\sigma)} g(\sigma) d\sigma$$

for $\tau \in [-r, 0]$. Since B generates a C_0 -semigroup on E , it follows from the Hille–Yosida theorem that

$$\begin{aligned} & \|f_n(\tau)\|_E \\ & \leq \frac{M}{(\lambda - \omega)^n} e^{\lambda\tau} \|\eta\|_E \sum_{p=0}^{n-1} \frac{[(\omega - \lambda)\tau]^p}{p!} \\ & \quad + \|g\|_{C_E} \left[\frac{M}{(\lambda - \omega)^n} e^{\lambda\tau} \sum_{p=0}^{n-1} \frac{[(\omega - \lambda)\tau]^p}{p!} + \frac{1}{(n-1)!} \int_{\tau}^0 (\sigma - \tau)^{n-1} e^{\lambda(\tau-\sigma)} d\sigma \right] \\ & \leq \frac{M}{(\lambda - \omega)^n} e^{\lambda\tau} e^{(\omega - \lambda)\tau} \|\eta\|_E \\ & \quad + \|g\|_{C_E} \left[\frac{M}{(\lambda - \omega)^n} e^{\lambda\tau} \sum_{p=0}^{n-1} \frac{[(\omega - \lambda)\tau]^p}{p!} + \frac{M}{(n-1)!} \int_{\tau}^0 (-\sigma)^{n-1} e^{(\lambda - \omega)\sigma} d\sigma \right] \\ & \leq \frac{M}{(\lambda - \omega)^n} \|\eta\|_E + \|g\|_{C_E} [\dots] \end{aligned}$$

for $\tau \in [-r, 0]$. If we compute the term $[\dots]$ we obtain

$$\frac{M}{(\lambda - \omega)^n} e^{\lambda\tau} \sum_{p=0}^{n-1} \frac{[(\omega - \lambda)\tau]^p}{p!} + \frac{M}{(n-1)!} \int_{\tau}^0 (-\sigma)^{n-1} e^{(\lambda - \omega)\sigma} d\sigma = \frac{M}{(\lambda - \omega)^n}$$

for $\tau \in [-r, 0]$. Therefore,

$$\|(\lambda - \mathcal{A})^{-n}\| \leq \frac{M}{(\lambda - \omega)^n} \quad \text{for all } \lambda > \omega \text{ and } n \in \mathbb{N}. \blacksquare$$

Since $D(B)$ is dense in E , we have $X_0 := \overline{D(\mathcal{A})} = \{0\} \times C_E$, which we identify with C_E . From Proposition 1.1 it follows that the part \mathcal{A}_0 of \mathcal{A} in X_0 generates a C_0 -semigroup on X_0 , which we can identify with the following C_0 -semigroup on C_E :

$$(T_0(t)f)(\tau) = \begin{cases} f(t + \tau) & \text{if } -r \leq t + \tau \leq 0, \\ S(t + \tau)f(0) & \text{if } t + \tau \geq 0, \end{cases}$$

for $\tau \in [-r, 0]$ (see [Na], B-IV, p. 220). Let $(T_{-1}(t))_{t \geq 0}$ denote the extrapolated semigroup of $(T_0(t))_{t \geq 0}$ on X . Since $L(\cdot) \in C([0, T], \mathcal{L}_s(C_E, E))$ and

$X \hookrightarrow F(\mathcal{A}_{-1})$, we have

$$C(\cdot) := \begin{pmatrix} 0 & L(\cdot) \\ 0 & 0 \end{pmatrix} \in C([0, T], \mathcal{L}_s(X_0, F(\mathcal{A}_{-1}))).$$

Consequently, the assumptions of Theorem 2.3 are satisfied and hence there exists an evolution family $(U(t, s))_{(t,s) \in \Delta}$ on C_E satisfying

$$(10) \quad \begin{pmatrix} 0 \\ U(t, s)f \end{pmatrix} = \begin{pmatrix} 0 \\ T_0(t-s)f \end{pmatrix} + \int_s^t T_{-1}(t-\sigma) \begin{pmatrix} L(\sigma)U(\sigma, s)f \\ 0 \end{pmatrix} d\sigma,$$

for $f \in C_E$ and $(t, s) \in \Delta$.

We can now state the main result of this section.

THEOREM 3.2. *Let $(B, D(B))$ be a generator of a C_0 -semigroup $(S(t))_{t \geq 0}$ on a Banach space E . Let $L(\cdot) \in C([0, T], \mathcal{L}_s(C_E, E))$. For every $f \in C_E$, the non-autonomous retarded partial differential equation (NRDE) has a unique mild solution x on $[0, T]$. This means that $x \in C([0, T], E)$ and satisfies*

$$(11) \quad \begin{cases} x(t) = S(t-s)f(0) + \int_s^t S(t-\sigma)L(\sigma)x_\sigma d\sigma, \\ x(\tau) = f(\tau-s), \quad s-r \leq \tau \leq s, \quad 0 \leq s < t \leq T. \end{cases}$$

Moreover, the function x is given by

$$(12) \quad x(t) = (U(t, s)f)(0), \quad 0 \leq s \leq t \leq T,$$

where $(U(t, s))_{(t,s) \in \Delta}$ is the evolution family given by (10).

Proof. First, we remark that for all $\eta \in E$ we have

$$R_1 \begin{pmatrix} \eta \\ 0 \end{pmatrix} := \begin{pmatrix} 0 \\ e(\cdot)(I-B)^{-1}\eta \end{pmatrix} \in D(\mathcal{A}),$$

where $e(\tau) := e^\tau, \tau \in [-r, 0]$. It follows from (9) that

$$(13) \quad (I-\mathcal{A})R_1 \begin{pmatrix} \eta \\ 0 \end{pmatrix} = \begin{pmatrix} \eta \\ 0 \end{pmatrix}.$$

From (10) and (13) we obtain

$$(14) \quad \begin{aligned} & \begin{pmatrix} 0 \\ U(t, s)f \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ T_0(t-s)f \end{pmatrix} + \int_s^t T_{-1}(t-\sigma)(I-\mathcal{A})R_1 \begin{pmatrix} L(\sigma)U(\sigma, s)f \\ 0 \end{pmatrix} d\sigma \\ &= \begin{pmatrix} 0 \\ T_0(t-s)f \end{pmatrix} \\ &+ (I-\mathcal{A}_{-1}) \int_s^t T_0(t-\sigma) \begin{pmatrix} 0 \\ e(\cdot)(I-B)^{-1}L(\sigma)U(\sigma, s)f \end{pmatrix} d\sigma \end{aligned}$$

$$\begin{aligned} &= \begin{pmatrix} 0 \\ T_0(t-s)f \end{pmatrix} \\ &+ (I-\mathcal{A}_{-1}) \left(\int_s^t T_0(t-\sigma)e(\cdot)(I-B)^{-1}L(\sigma)U(\sigma, s)f d\sigma \right) \end{aligned}$$

for $(t, s) \in \Delta$. If we put $\eta(\sigma) := L(\sigma)U(\sigma, s)f$ for $\sigma \in [s, t]$ and $0 \leq s < t \leq T$, then we have

$$\begin{aligned} h(\tau) &:= \int_s^t (T_0(t-\sigma)e(\cdot)(I-B)^{-1}\eta(\sigma))(\tau) d\sigma \\ &= \begin{cases} \int_s^{t+\tau} S(t+\tau-\sigma)(I-B)^{-1}\eta(\sigma) d\sigma \\ \quad + \int_{t+\tau}^t e^{t+\tau-\sigma}(I-B)^{-1}\eta(\sigma) d\sigma & \text{if } t+\tau-s \geq 0, \\ \int_s^t e^{t+\tau-\sigma}(I-B)^{-1}\eta(\sigma) d\sigma & \text{if } -r \leq t+\tau-s \leq 0, \end{cases} \end{aligned}$$

for $\tau \in [-r, 0]$. Hence, $h \in C_B^1, h(0) \in D(B)$ and

$$h'(\tau) = \begin{cases} \int_s^{t+\tau} S(t+\tau-\sigma)B(I-B)^{-1}\eta(\sigma) d\sigma \\ \quad + \int_{t+\tau}^t e^{t+\tau-\sigma}(I-B)^{-1}\eta(\sigma) d\sigma & \text{if } t+\tau-s \geq 0, \\ \int_s^t e^{t+\tau-\sigma}(I-B)^{-1}\eta(\sigma) d\sigma & \text{if } -r \leq t+\tau-s \leq 0, \end{cases}$$

for $\tau \in [-r, 0]$ and $0 \leq s < t \leq T$. Consequently, $\begin{pmatrix} 0 \\ h \end{pmatrix} \in D(\mathcal{A})$ and

$$\begin{aligned} (I-\mathcal{A}_{-1}) \begin{pmatrix} 0 \\ h \end{pmatrix}(\tau) &= (I-\mathcal{A}) \begin{pmatrix} 0 \\ h \end{pmatrix}(\tau) \\ &= \begin{pmatrix} h'(0) - Bh(0) \\ h - h' \end{pmatrix}(\tau) = \begin{pmatrix} 0 \\ h - h' \end{pmatrix}(\tau) \\ &= \begin{pmatrix} 0 \\ \begin{cases} \int_s^{t+\tau} S(t+\tau-\sigma)\eta(\sigma) d\sigma & \text{if } t+\tau-s \geq 0 \\ 0 & \text{if } -r \leq t+\tau-s \leq 0 \end{cases} \end{pmatrix} \end{aligned}$$

for $\tau \in [-r, 0]$ and $0 \leq s < t \leq T$. So by (14) we obtain

$$(15) \quad \begin{aligned} & (U(t, s)f)(\tau) \\ &= \begin{cases} S(t+\tau-s)f(0) \\ \quad + \int_s^{t+\tau} S(t+\tau-\sigma)L(\sigma)U(\sigma, s)f d\sigma & \text{if } t+\tau-s \geq 0, \\ f(t+\tau-s) & \text{if } -r \leq t+\tau-s \leq 0, \end{cases} \end{aligned}$$

for $\tau \in [-r, 0]$ and $0 \leq s < t \leq T$. If, for $0 \leq s < t \leq T$, we put $x(t) := (U(t, s)f)(0)$, then it follows from (15) that

$$(16) \quad x(t) = S(t-s)f(0) + \int_s^t S(t-\sigma)L(\sigma)U(\sigma, s)f d\sigma$$

and

$$(17) \quad (U(t, s)f)(\tau) = \begin{cases} f(t+\tau-s) & \text{if } -r \leq t+\tau-s \leq 0, \\ x(t+\tau) & \text{if } t+\tau-s \geq 0. \end{cases}$$

If we extend x to the interval $[s - r, s]$ by

$$x(\tau) = f(\tau - s), \quad \tau \in [s - r, s],$$

then from (17) we obtain

$$(18) \quad U(t, s)f = x_t \quad \text{for } (t, s) \in \Delta.$$

Therefore, it follows from (16) that (11) holds and the theorem is proved. ■

Let I be an interval and F be a Banach space. We denote by $C^\theta(I, F)$ the space of all functions f Hölder continuous with exponent θ , $0 < \theta < 1$, on I , i.e., there is a constant C such that

$$\|f(t) - f(s)\|_F \leq C|t - s|^\theta \quad \text{for } s, t \in I.$$

The Hölder space of order θ , $0 < \theta < 1$, associated with a C_0 -semigroup $(S(t))_{t \geq 0}$ with generator $(B, D(B))$ on a Banach space E is

$$D_B(\theta, \infty) := \left\{ x \in E : \sup_{t \in (0, T]} \frac{1}{t^\theta} \|S(t)x - x\|_E < \infty \right\}.$$

Then $D_B(\theta, \infty)$ is the Lions interpolation space between $D(B)$ and E (see [Li]).

Let $s \in [0, T]$. We say that (NRDE) has a classical solution x on $[0, T]$ if x is continuous on $[0, T]$, continuously differentiable on $(s, T]$, $x(t) \in D(B)$ for $t \in (s, T]$ and (NRDE) is satisfied on $[0, T]$.

We establish some sufficient conditions on the semigroup $(S(t))_{t \geq 0}$ and $L(\cdot)$ to assure that the mild solution given by (11) is a classical solution of (NRDE).

PROPOSITION 3.3. *Let $(B, D(B))$ be a generator of an analytic semigroup $(S(t))_{t \geq 0}$ on a Banach space E . Let $L(\cdot) \in C^\theta([0, T], \mathcal{L}(C_E, E))$. For every $f \in C_E$ such that $f(0) \in D_B(\theta, \infty)$ the mild solution x on $[0, T]$ given by (11) is a classical solution of the non-autonomous retarded differential equation (NRDE).*

Proof. Let $s \in [0, T]$. From (11) we have

$$(19) \quad x_s(t) = S(t)f(0) + \int_0^t S(t - \sigma)L_s(\sigma)(x_s)_\sigma d\sigma, \quad t \in [0, T],$$

where $L_s(\sigma) = L(\sigma + s)$. It follows from (18) and Theorem 2.3 that the function $g := L_s(\cdot)(x_s) : [0, T] \rightarrow E$ is continuous. In particular $g \in L^{1/(1-\theta)}(0, T; E)$. So by Theorem 4.3.1 of [Pa], we have

$$v \in C^\theta([0, T], E),$$

where $v(t) := \int_0^t S(t - \sigma)L_s(\sigma)(x_s)_\sigma d\sigma$ ($t \in [0, T]$).

Since $f(0) \in D_B(\theta, \infty)$, the function $[0, T] \ni t \mapsto S(t)f(0)$ belongs to $C^\theta([0, T], E)$ and therefore the function x_s given by (19) is Hölder continuous

with exponent θ from $[0, T]$ into E . From $L(\cdot) \in C^\theta([0, T], \mathcal{L}(C_E, E))$ we obtain $g \in C^\theta([0, T], E)$. Hence it follows from Corollary 4.3.3 of [Pa] that x_s is continuously differentiable on $(0, T]$, $x_s(t) \in D(B)$ for $t \in (0, T]$ and

$$x'(s + t) = Bx(s + t) + L(s + t)x_{t+s}, \quad t \in (0, T].$$

This implies that x is a classical solution of (NRDE) on $[0, T]$. ■

The following example gives a concrete application of Proposition 3.3.

EXAMPLE 3.4. Let Ω be a bounded open set of \mathbb{R}^n with sufficiently smooth boundary Γ . On the Banach space $E := C_0(\bar{\Omega})$ of all continuous functions vanishing at the boundary Γ we consider the Laplace operator Δ_x with maximal domain $D(\Delta_x)$. Then it is well known that Δ_x generates an analytic semigroup $(S(t))_{t \geq 0}$.

Let $L \in \mathcal{L}(E)$ and $k : [0, T] \times \bar{\Omega} \ni (t, x) \mapsto k(x, t) \in \mathbb{R}$ be uniformly Hölder continuous with exponent $\theta \in (0, 1)$ with respect to the variable t . For $t \in [0, T]$, we consider the bounded linear operator $L(t) : C_E \rightarrow E$ defined by

$$(L(t)f)(x) = k(t, x)(Lf(-r))(x) \quad \text{for } x \in \bar{\Omega}.$$

Then

$$L(\cdot) \in C^\theta([0, T], \mathcal{L}(C_E, E)).$$

On the other hand, for $\theta \in (0, 1)$ one has (see [Lu], Thm. 2.10, and [Lu1], Thm. 3.1.29)

$$D_{\Delta_x}(\theta, \infty) = \begin{cases} C_0^{2\theta}(\bar{\Omega}), & \theta \neq 1/2, \\ C_0^2(\bar{\Omega}), & \theta = 1/2, \end{cases}$$

where

$$C_0^{p+\alpha}(\bar{\Omega}) := \{u \in C^p(\bar{\Omega}), u^{(p)} \in C^\alpha(\bar{\Omega}) \text{ and } u = 0 \text{ on } \Gamma\} \\ (p \in \mathbb{N}, \alpha \in (0, 1)).$$

So by Proposition 3.3, we see that for $f(0) \in C_0^{2\theta}(\bar{\Omega})$, $\theta \in (0, 1)$, $\theta \neq 1/2$ (or $f(0) \in C_0^2(\bar{\Omega})$, if $\theta = 1/2$), the retarded partial differential equation

$$\begin{cases} \frac{\partial}{\partial t} u(t, x) = \Delta_x u(t, x) + k(t, x)(Lu(t - r))(x), & x \in \bar{\Omega}, 0 \leq s < t \leq T, \\ u(\tau, \cdot) = f(\tau - s), & s - r \leq \tau \leq s, \end{cases}$$

has a unique classical solution.

Acknowledgements. A substantial part of the results of this paper was obtained during a visit of the author to the Rome university *La Sapienza*. The author is indebted to CNR for supporting this visit. He further thanks E. Sinestrari for his help and encouragement.

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Received March 25, 1996

(3642)