

## A natural parameter of a curve in the symplectic space

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The object of this note is to define a natural parameter  $\vartheta$  of a curve in the symplectic space  $G_{2n}$  of dimension  $2n$ , i.e. in the affine space of the same dimension with the symplectic group  $Sp_{2n}$  [4] of transformations. The parameter  $\vartheta$  will be defined in a geometric way — as for example in [1], p. 8 the arc  $s$  of a curve in the Euclidean space is defined. The parameter  $s$  is such a parameter that the length of the tangent vector  $\mathbf{x}'(s)$  of a curve  $x = x(s)$  in the Euclidean space is equal to 1. But for two points in  $G_{2n}$  there is no invariant with respect to the symplectic transformations. We take therefore two vectors  $\mathbf{x}^{(\varrho)}(\vartheta)$  and  $\mathbf{x}^{(\varrho+1)}(\vartheta)$  attached to a point of a curve in  $G_{2n}$ ; the (symplectic) scalar product of these two vectors is equal to 1;  $\varrho$  is the order of the derivative of the vector  $\mathbf{x} = \mathbf{x}(\vartheta)$ , where  $\vartheta$  is our natural parameter and denotes the rank, defined in section 3, of the curve.

Parameter  $\vartheta$  may be defined for a more extensive class of curves than the class with parameter  $s$  defined in [2] or [5].

Our definition of a curve is based on the same idea as the definition of Nomizu [3]. Nomizu defined a curve of class  $C^\infty$  as an equivalence class of parametrized curves of class  $C^\infty$ . It is not required in this paper that the equivalent curves be of the same class.

**1.** Let the space  $G_{2n}$  be referred to a symplectic frame. Thus

$$\Omega = \sum_{i=1}^n [\mathbf{x}^i \mathbf{x}^{n+i}]$$

is its fundamental form. The value of the exterior form  $\Omega$  for two vectors  $\mathbf{x}_l = (\mathbf{x}_l^1, \dots, \mathbf{x}_l^{2n})$ ,  $l = 1, 2$ , denoted by  $\Omega[\mathbf{x}_1, \mathbf{x}_2]$  and equal to

$$\sum_{i=1}^n (\mathbf{x}_1^i \mathbf{x}_2^{n+i} - \mathbf{x}_1^{n+i} \mathbf{x}_2^i),$$

is the only invariant ([4], p. 122) of the pair of vectors  $\mathbf{x}_1, \mathbf{x}_2$  with respect to the transformations of  $Sp_{2n}$ . This invariant will be called the *scalar product of two vectors* and also denoted by  $[\mathbf{x}_1, \mathbf{x}_2]$  or  $\sum_{i=1}^n [\mathbf{x}_1^i, \mathbf{x}_2^{n+i}]$ .

The value of the  $k$ th exterior power of  $\Omega$ , i.e. the value of the form

$$[\Omega^k] = \sum_{i_1, \dots, i_k=1}^n [\Pi_{i_1} \dots \Pi_{i_k}],$$

where  $\Pi_i = [\mathbf{x}^i \mathbf{x}^{n+i}]$ , for  $2k$  vectors  $\mathbf{x}_1, \dots, \mathbf{x}_{2k}$  denoted by  $\Omega^k[\mathbf{x}_1, \dots, \mathbf{x}_{2k}]$  or  $[\mathbf{x}_1 \dots \mathbf{x}_{2k}]$ , is the only invariant of these vectors. This definition was used by Yaglom [5] to define the arc  $s$  of a curve in  $G_{2n}$  by the following formulas:

$$s = \begin{cases} \int [\mathbf{x}' \mathbf{x}'' \dots \mathbf{x}^{(2n)}]^{1/n(2n+1)} dt & \text{for } n \text{ even,} \\ \int |[\mathbf{x}' \mathbf{x}'' \dots \mathbf{x}^{(2n)}]|^{1/n(2n+1)} dt & \text{for } n \text{ odd,} \end{cases}$$

where the vector  $\mathbf{x} = \mathbf{x}(t)$  defines a curve of  $G_{2n}$  and the superscripts denote differentiation. The volume of the parallelepiped constructed on vectors  $\mathbf{x}'(s), \mathbf{x}''(s), \dots, \mathbf{x}^{(2n)}(s)$ , i.e. the value of  $[\Omega^n]$  for these vectors, is equal to 1.

The author has defined [2] a parameter  $s$  of a curve in  $G_{2n}$  by the formula

$$(1) \quad s = \int [\mathbf{x}' \mathbf{x}'' ]^{1/3} dt$$

assuming that  $[\mathbf{x}' \mathbf{x}'' ] \neq 0$ . The scalar product  $[\mathbf{x}'(s) \mathbf{x}''(s)]$  of two vectors  $\mathbf{x}'(s)$  and  $\mathbf{x}''(s)$ , where  $s$  is the parameter defined by (1), is equal to 1.

**2.** By a *parametrized curve*  $\mathfrak{R}(t)$  of class  $C^{\mu_i}$ , where  $\mu_i$  is zero, an integer,  $\infty$  or  $\omega$ , we mean a mapping of a certain interval  $T = [a, b]$  into  $G_{2n}$  defined by  $x^a = x^a(t)$ ,  $a = 1, \dots, 2n$ , where  $x^a(t)$  are functions of class  $C^{\mu_i}$  on  $T$ . The parametrized curve  $\mathfrak{R}(t)$  of class  $C^{\mu_i}$  is said to be *equivalent* to the parametrized curve  $\mathfrak{R}(\bar{t})$  of class  $C^{\mu_i}$  if there exists a strictly monotonic and continuous function  $\bar{t} = \psi(t)$ ,  $\bar{t} \in \bar{T}$ , such that  $x^a(t) = \bar{x}^a(\psi(t))$  for every  $t \in T$ . This mapping will be called an *admissible transformation* of the parameter. The maximal cardinal number of all numbers  $\mu_i$  obtained by any admissible change of the parameter  $t$  is denoted by  $\mu$ . The equivalence class of a parametrized curve  $\mathfrak{R}(t)$  of class  $C^{\mu_i}$  will be called the *curve*  $\mathfrak{R}$  of class  $C^\mu$ .

Instead of writing "a parametrized curve  $\mathfrak{R}(t)$ " we will write "a curve  $\mathfrak{R}(t)$ ".

Two equivalent curves are the same sets of points in  $G_{2n}$ . Double points are to be counted twice, triple points — thrice and so on.

A curve  $\mathfrak{R}$  is *essentially imbedded* in  $G_{2n}$  if neither the curve  $\mathfrak{R}$  nor any of its arcs may be imbedded in a subspace of  $G_{2n}$ . We assume that the curve which we consider, except in section 5, is such a curve.

We assume that all derivatives that we use exist. For a curve  $\mathfrak{R}(t) \in \mathfrak{R}$  of class  $C^{2n+1}$  there exist vectors  $\mathbf{x}'(t), \dots, \mathbf{x}^{(2n)}(t)$  continuous and independent.

### 3. The expressions

$$(2) \quad \sum_{i=1}^n \left[ \frac{d^h \mathbf{x}^i}{dt^h} \cdot \frac{d^k \mathbf{x}^{n+i}}{dt^k} \right] = K_{h|k}(t), \quad h < k, \quad k = 1, 2, \dots,$$

are the differential invariants of order  $k$  with respect to the symplectic transformations of a curve  $\mathfrak{R}(t)$ . From Theorem I in [2] it follows that

$$K_{h|k}(t) = \sum_{p=1}^m (-1)^p \binom{k-h-p}{p-1} K_{h+p-1|h+p}^{(k-h-2p+1)}(t),$$

$$m = \left[ \frac{k-h+1}{2} \right], \quad h = 1, \dots, k-1,$$

where  $(k-h-2p+1)$  denotes differentiation of order  $k-h-2p+1$  and the brackets  $[ ]$  denote "entier".

Let  $p(t)$  denote a point of a curve  $\mathfrak{R}(t)$ , i.e. the end of the vector  $\mathbf{x}(t)$ . If  $\bar{t} = \psi(\bar{t})$  is an admissible change of parameter  $t$  of the curve,  $p(\bar{t})$  is the same point. Denote by  $p$  all incident points of equivalent parametrized curves.

Assign to every point  $p(t)$  of a curve  $\mathfrak{R}(t)$  a set of plane elements  $E_1(t) = \{\mathbf{x}'(t), \mathbf{x}''(t)\}$ ,  $E_2(t) = \{\mathbf{x}''(t), \mathbf{x}'''(t)\}$ , ...,  $E_{2n}(t) = \{\mathbf{x}^{(2n)}(t), \mathbf{x}^{(2n+1)}(t)\}$  and a set of invariants

$$K_{1|2}(t), \quad K_{2|3}(t), \quad \dots, \quad K_{2n|2n+1}(t).$$

The plane element  $E_k(t)$  is *involutive* if the value of the form  $\Omega$  for vectors  $\mathbf{x}^{(k)}(t)$  and  $\mathbf{x}^{(k+1)}(t)$  is equal to zero.

A point  $p(t) \in \mathfrak{R}(t)$  is said to be of *rank*  $\varrho$  if the elements  $E_1(t), \dots, E_{\varrho-1}(t)$  are involutive planes and the element  $E_{\varrho}(t)$  is not an involutive plane. This definition is equivalent to the following one: a point  $p(t) \in \mathfrak{R}(t)$  is said to be of *rank*  $\varrho$  if

$$K_{1|2}(t) = \dots = K_{\varrho-1|\varrho}(t) \quad \text{and} \quad K_{\varrho|\varrho+1}(t) \neq 0.$$

We have the following

**LEMMA 1.** *If the rank of a point  $p(t)$  of a curve  $\mathfrak{R}(t)$  is  $\varrho$ , then the rank of the point  $p(\bar{t})$  of the equivalent curve  $\mathfrak{R}(\bar{t})$  is also  $\varrho$ .*

In fact, we have

$$(4) \quad \bar{K}_{\sigma-1|\sigma}(\bar{t}) = \sum_{k,h=1}^{\sigma} \beta_{hk}(t) K_{h|k}(t), \quad \sigma = 1, \dots, h < k,$$

where  $\beta_{hk}(t)$  are known functions. From the assumptions of the lemma and from (3) it follows that, in (4),  $K_{h|k}(t) = 0$  for  $k \leq \varrho$ . Thus  $\bar{K}_{1|2}(\bar{t}) = \dots = \bar{K}_{\varrho-1|\varrho}(\bar{t}) = 0$ . But

$$(5) \quad \bar{K}_{\varrho|\varrho+1}(\bar{t}) = \left(\frac{dt}{d\bar{t}}\right)^{2\varrho+1} K_{\varrho|\varrho+1}(t) \neq 0,$$

which proves the lemma.

A point  $p \in \mathfrak{R}$  is said to be of rank  $\varrho$  if  $p(t) \in \mathfrak{R}(t)$  is of rank  $\varrho$ . A curve  $\mathfrak{R}$  is of rank  $\varrho$  if its every point is of rank  $\varrho$ . In what follows we assume that the curve  $\mathfrak{R}$  is of rank  $\varrho$ , i.e. that

$$(6) \quad K_{\varrho|\varrho+1}(t) \neq 0$$

for every  $t \in T$ .

LEMMA 2. *The rank of any curve  $\mathfrak{R}$  imbedded in  $G_{2n}$  is not greater than  $n$ .*

In fact, if  $K_{1|2} = K_{2|3} = \dots = K_{n|n+1} = 0$  then for a curve  $\mathfrak{R}(t) \in \mathfrak{R}$ , as follows from (3),  $K_{h|k}(t) = 0$  ( $h < k$ ) for  $k = 1, \dots, n+1$ . Hence there exists a set of  $n+1$  independent vectors  $\mathbf{x}'(t), \dots, \mathbf{x}^{(n+1)}(t)$  such that the linear space expanded on these vectors would be an involutive subspace of dimension  $n+1$ , which is impossible ([4], p. 84). Thus Lemma 2 is proved.

LEMMA 3. *If a curve  $\mathfrak{R}(t)$  is of rank  $\varrho$ , then, for every  $t \in \text{int } T$ , there exists such a neighbourhood  $U$  that the inequality  $[\mathbf{x}^{(\varrho)}(t) \mathbf{x}^{(\varrho)}(\tau)] \neq 0$  holds for every  $\tau \in U$  except  $\tau = t$ .*

The statement follows from

$$\left(\frac{d}{d\tau} [\mathbf{x}^{(\varrho)}(t) \mathbf{x}^{(\varrho)}(\tau)]\right)_{\tau=t} = K_{\varrho|\varrho+1}(t) \neq 0 \quad \text{and} \quad [\mathbf{x}^{(\varrho)}(t) \mathbf{x}^{(\varrho)}(\tau)]_{\tau=t} = 0.$$

For the end-points of curve  $\mathfrak{R}(t)$  there exist right-hand and left-hand neighbourhoods that satisfy the statement made in Lemma 3.

4. Let  $\varepsilon_0(t)$  denote the length (i.e. the difference  $|t_2 - t_1|$ , where  $t_1$  and  $t_2$  are the end-points of an interval) of the largest neighbourhood of a point  $t \in \text{int } T$  for which Lemma 3 is satisfied. Particularly,  $\varepsilon_0(t)$  may be equal to the length of  $T$ . It is easy to see that  $\inf \varepsilon_0(t) \neq 0$ . By  $\varepsilon_1$  and  $\varepsilon_2$  we denote the lengths of the largest right-hand and left-hand neighbourhoods of the end-points of  $T$ , respectively.

Choose a set of points  $a = t_0, t_1, \dots, t_m = b$  belonging to  $T$  in such a way that  $|t_i - t_{i-1}| < \varepsilon/2$  ( $i = 1, \dots, m$ ), where  $\varepsilon = \min(\inf \varepsilon_0(t), \varepsilon_1, \varepsilon_2)$ . From assumption (6) it follows that the function  $K_{e|e+1}(t)$  does not change its sign and, as follows from Lemma 3,

$$(7) \quad \text{sign}[\mathbf{x}^{(e)}(t_{i-1})\mathbf{x}^{(e)}(t_i)] = \text{const} \neq 0$$

for every  $i$ .

Let  $\Delta\vartheta_i$  denote the invariant

$$(8) \quad \Delta\vartheta_i = \{[\mathbf{x}^{(e)}(t_{i-1})\mathbf{x}^{(e)}(t_i)](\Delta t_i)^{2e}\}^{1/(2e+1)},$$

where  $\Delta t_i = t_i - t_{i-1}$ . By the mean value theorem we have

$$(9) \quad \mathbf{x}^{(e)}(t_i) = \mathbf{x}^{(e)}(t_{i-1}) + \mathbf{x}^{(e+1)}(\theta_i)\Delta t_i,$$

where  $t_{i-1} < \theta_i < t_i$ . From (8) and (9) we have

$$\Delta\vartheta_i = [\mathbf{x}^{(e)}(t_{i-1})\mathbf{x}^{(e+1)}(\theta_i)]^{1/(2e+1)}\Delta t_i.$$

The integral

$$(10) \quad \lim_{m \rightarrow \infty} \sum_{i=1}^m \Delta\vartheta_i = \int_a^b [\mathbf{x}^{(e)}(t)\mathbf{x}^{(e+1)}(t)]^{1/(2e+1)} dt$$

is called the *symplectic length of the curve*  $\mathfrak{K}$ . From (7) it follows that

$$(11) \quad \vartheta = \int_a^t [\mathbf{x}^{(e)}(t)\mathbf{x}^{(e+1)}(t)]^{1/(2e+1)} dt$$

is a strictly monotonic function of  $t$ . From (11) and (5) we get

$$\left(\frac{d\vartheta}{dt}\right)^{2e+1} = K_{e|e+1}(t) = \left(\frac{d\vartheta}{dt}\right)^{2e+1} K_{e|e+1}(\vartheta);$$

thus for the curve  $\mathfrak{K}(\vartheta)$  we have

$$(12) \quad [\mathbf{x}^{(e)}(\vartheta)\mathbf{x}^{(e+1)}(\vartheta)] = 1.$$

The parameter for which equation (12) is satisfied will be called the *natural parameter* of the curve  $\mathfrak{K}$  of rank  $e$ .

The natural parameter is defined up to an additive constant.

Integral (10) does not change its value by any admissible transformation of the parameter of the curve  $\mathfrak{K}$ . Thus the natural parameter of a curve  $\mathfrak{K}$  is an invariant with respect to such transformations.

The expression

$$d\vartheta^{2e+1} = [d^e \mathbf{x} d^{e+1} \mathbf{x}]$$

is called the *element of the symplectic arc* of a curve  $\mathfrak{K}$  of rank  $e$ .

The class of differentiability of function (11) is lower than that of the curve  $\mathfrak{R}(t)$  and the difference is equal to  $\rho$ . Thus, if a curve  $\mathfrak{R}$  of rank  $\rho$  is of class  $C^\mu$ , then the curve  $\mathfrak{R}(\vartheta)$  is of class  $C^{\mu-\rho}$ . If the class of a curve  $\mathfrak{R}$  is equal to  $C^{2n+1}$ , then the invariants  $K_{1|2}, K_{2|3}, \dots, K_{2n|2n+1}$  and the vectors  $\mathbf{x}', \mathbf{x}'', \dots, \mathbf{x}^{(2n+1)}$  exist and are continuous. But the natural parameter may be defined on the curve of class  $C^\mu$  ( $\mu \geq 2\rho + 1$ ) and then the vectors  $\mathbf{x}'(\vartheta), \dots, \mathbf{x}^{(\rho+1)}(\vartheta)$  are continuous.

Therefore we have the following

**THEOREM.** *If a curve  $\mathfrak{R}$ , essentially imbedded in  $G_{2n}$ , is of rank  $\rho$  and of class at least  $C^\mu$  ( $\mu \geq 2\rho + 1$ ), then there exists one and only one (up to an additive constant) parametrized curve  $\mathfrak{R}(\vartheta) \in \mathfrak{R}$  which is of class  $C^{\rho+1}$  and  $[\mathbf{x}^{(\rho)}(\vartheta) \mathbf{x}^{(\rho+1)}(\vartheta)] = 1$ .*

**5.** Denote by  $G_{2\gamma;\beta}$  ( $\gamma = 1, \dots, n, 2\gamma + \beta < 2n$ ) a linear subspace of  $G_{2n}$  of dimension  $2\gamma + \beta$ , where  $\beta$  is the number of independent and distinguished vectors of  $G_{2n}$ . A vector of a linear subspace of the symplectic space is called a *distinguished* one if it is in involution with all other vectors of the subspace ([4], p. 86).

The theorem of section 4 may be formulated in a more general form:

*If a curve  $\mathfrak{R}$  of rank  $\rho$  is essentially imbedded in a  $G_{2\gamma;\beta}$  and if it is of class at least  $C^{2\rho+1}$ , then there exists one and only one (up to an additive constant) parametrized curve  $\mathfrak{R}(\vartheta) \in \mathfrak{R}$  which is of class  $C^{\rho+1}$  and  $K_{\rho|\rho+1} = 1$ .*

The rank of a curve  $\mathfrak{R}$  essentially imbedded in  $G_{2\gamma;\beta}$  is not greater than  $\gamma$ .

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