

Description of a class of multivalued differential equations with almost weakly stable trivial solution

by MICHAŁ KISIELEWICZ (Zielona Góra)

Abstract. In the present paper a multivalued differential relation of the form

$$(1) \quad \dot{x} \in F(t, x),$$

is considered. It is shown that the class \mathcal{A} of all multivalued mappings F defined on $[0, \infty) \times \mathbf{R}^n$ for which the trivial solution $x_F = 0$ of (1) is almost weak stable is an $F_{\sigma\delta\sigma}$ set in any complete metric space.

1. Introduction. It is the purpose of this note to present a description the class of all multivalued differential equations of the form

$$(1) \quad \dot{x} \in F(t, x)$$

with the almost weakly stable trivial solution. It is shown that the class \mathcal{A} of all multivalued mappings F defined on $[0, \infty) \times \mathbf{R}^n$ for which the trivial solution $x_F \equiv 0$ of (1) is almost weak stable, is an $F_{\sigma\delta\sigma}$ set in any complete metric space. The weak stability theorem for multivalued differential equations of form (1) has been proved in [5].

2. Notation and basic definitions. Let \mathbf{R}^n be the n -dimensional Euclidean space, 0 its zero element, $\|x\|$ the norm of $x \in \mathbf{R}^n$. For non-empty sets $A, B \subset \mathbf{R}^n$ we use the Hausdorff distance $h(A, B) = \max[r(A, B), r(B, A)]$, where $r(A, B) = \sup\{\alpha(x, B) : x \in A\}$ and $\alpha(x, B) = \inf\{\|x - y\| : y \in B\}$. The set of all non-empty compact convex subsets of \mathbf{R}^n is denoted by Ω^n . Let \mathcal{C}_T denote the Banach space of continuous mappings of $[0, T]$ into \mathbf{R}^n and let \mathcal{L}_T^1 be the Banach space of (equivalence classes of) Lebesgue integrable mappings of $[0, T]$ into \mathbf{R}^n .

We say that $F: [0, \infty) \times \mathbf{R}^n \rightarrow \Omega^n$ satisfies Carathéodory type conditions if $F(\cdot, x)$ is measurable in $t \geq 0$ for every fixed $x \in \mathbf{R}^n$, $F(t, \cdot)$ is continuous in $x \in \mathbf{R}^n$ for fixed $t \geq 0$ and there is an $m_F \in \bigcap_{T>0} \mathcal{L}_T^1$ such that $\|F(t, x)\|_h \leq m_F(t)$ for a.e. $t \geq 0$ and $x \in \mathbf{R}^n$; $\|F(t, x)\|_h = h(F(t, x), \{0\})$.

It is known (see [1], [3]) that for every F satisfying Carathéodory type conditions and for every $T > 0$, $x_0 \in \mathbf{R}^n$ and $t_0 \geq 0$ there exists an absolutely continuous mapping $x(\cdot; t_0, x_0)$ of $[0, T]$ into \mathbf{R}^n such that $x(t_0; t_0, x_0) = x_0$ and $\dot{x}(t; t_0, x_0) \in F(t, x(t; t_0, x_0))$ for a.e. $t \in [0, T]$. If the above conditions are satisfied for each $T \geq 0$, then the function $x(\cdot; t_0, x_0) \in \bigcap_{T>0} \mathcal{C}_T$ will be called a *trajectory* of (1) corresponding to (t_0, x_0, F) . The union of all trajectories of (1) corresponding to (t_0, x_0, F) will be denoted by $S(t_0, x_0, F)$.

Let \mathcal{N} denote the set of all positive integers and let $\mathcal{C} = \bigcap_{T>0} \mathcal{C}_T$. By p_T we shall mean the seminorm of $x \in \mathcal{C}_T$ defined by $p_T(x) = \sup \{\|x(t)\| : 0 \leq t \leq T\}$. It is known (see Yosida, *Functional analysis*, 1968, p. 23) that the space \mathcal{C} together with the metric d defined by

$$d(x, y) = \sum_{T=1}^{\infty} \frac{1}{2^T} \cdot \frac{p_T(x-y)}{1+p_T(x-y)}$$

for $x, y \in \mathcal{C}$ is a complete metric space.

In a similar way we construct the complete metric space (\mathcal{F}, ϱ) . For this, let us denote by \mathcal{F} the quotient space of all mappings $F: [0, \infty) \times \mathbf{R}^n \rightarrow \Omega^n$ satisfying Carathéodory type conditions determined by an equivalence relation \sim defined in the following way:

$$F \sim G \quad \text{iff} \quad F(t, x) = G(t, x) \quad \text{for all } x \in \mathbf{R}^n \text{ and a.e. } t \geq 0.$$

Similarly as in [4] it can be verified that $\varrho: \mathcal{F} \times \mathcal{F} \rightarrow \mathbf{R}^1$ defined by

$$\varrho(F, G) = \sum_{T=1}^{\infty} \frac{\varrho_T(F, G)}{1+\varrho_T(F, G)},$$

where

$$\varrho_T(F, G) = \sup \left\{ \int_0^T h(F(t, x), G(t, x)) dt : x \in \mathbf{R}^n \right\}$$

for $F, G \in \mathcal{F}$ is a metric in \mathcal{F} .

It is not difficult to verify that (\mathcal{F}, ϱ) is a complete metric space.

3. Almost weak stability. We shall consider multivalued differential equations of form (1) under the assumption that the right-hand side $F \in \mathcal{F}$ is such that $0 \in F(t, 0)$ for a.e. $t \in [0, T]$ and all $T > 0$. Denoting by \mathcal{F}_0 the set of all such mappings $F \in \mathcal{F}$, we see that \mathcal{F}_0 is a closed subset of \mathcal{F} . Suppose that $F \in \mathcal{F}_0$. The trivial solution $x_F \equiv 0$ of (1) is called to be *almost weakly stable* if for each $t_0 \geq 0$ and $\varepsilon > 0$ there is a $\delta > 0$ such that for every $x_0 \in \mathbf{B}(0, \delta)$ ⁽¹⁾ there exists a $x(\cdot, t_0, x_0) \in S(t_0, x_0, F)$ such that

⁽¹⁾ $\mathbf{B}(0, \delta)$ denotes the closed ball of \mathbf{R}^n .

$d(0, x(\cdot; t_0, x_0)) \leq \varepsilon$. In the sequel we shall use the following lemma (for the proof see [2], [3]).

LEMMA 1. Let $F \in \mathcal{F}$, $t_0 \geq 0$, $x_0 \in \mathbf{R}^n$. Then $x(\cdot, t_0, x_0) \in S(t_0, x_0, F)$ if and only if

1° $x(t_0; t_0, x_0) = x_0$,

2° for every $T > 0$ and each $t_1, t_2 \in [0, T], t_1 < t_2$, we have

$$x(t_2; t_0, x_0) - x(t_1; t_0, x_0) \in \int_{t_1}^{t_2} F(s, x(s; t_0, x_0)) ds,$$

where the integral is mean in Aumann's sense.

Now, let us introduce the following notation:

$$H(t_0, x_0, m) = \{F \in \mathcal{F} : \|F(t, x)\|_h \leq m(t) \text{ for a.e. } t \geq 0, x \in \mathbf{R}^n \text{ and } S(t_0, x_0, F) \neq \emptyset\},$$

where $m \in \bigcap_{T=1}^{\infty} \mathcal{L}_T^1$, $\|F(t, x)\|_h = h(F(\cdot), \{0\})$, $Q(t_0, x_0, m) = \mathcal{F}_0 \cap H(t_0, x_0, m)$

and

$$\mathcal{P}(t_0, x_0, m, \varepsilon) = \{F \in Q(t_0, x_0, m) : d(0, x(\cdot; t_0, x_0)) \leq \varepsilon\},$$

where $x(\cdot; t_0, x_0) \in S(t_0, x_0, F)$.

We shall need the following lemma:

LEMMA 2. $H(t_0, x_0, m)$ is a closed subset of \mathcal{F} for each $t_0 \geq 0, x_0 \in \mathbf{R}^n$ and $m \in \bigcap_{T>0} \mathcal{L}_T^1$.

Proof. For fixed $t_0 \geq 0, x_0 \in \mathbf{R}^n$ and $m \in \bigcap_{T>0} \mathcal{L}_T^1$ let $\{F_n\}$ be a sequence in $H(t_0, x_0, m)$ such that $\varrho(F_n, F_0) \rightarrow 0$ as $n \rightarrow \infty$. By the completeness of \mathcal{F} , we have $F_0 \in \mathcal{F}$. It remains to show that $F_0 \in H(t_0, x_0, m)$. It is not difficult to see that $\|F_0(t, x)\|_h \leq m(t)$ for a.e. $t \geq 0$ and $x \in \mathbf{R}^n$. Let $\{x_n(\cdot; t_0, x_0)\}$ be a sequence of trajectories of (1) corresponding to $F = F_n$. Then $x_n(t_0; t_0, x_0) = x_0$ and $\dot{x}_n(t; t_0, x_0) \in F_n(t; x_n(t; t_0, x_0))$ for a.e. $t \in [0, T]$ and each $T > 0$.

By the definition of the metric ϱ , from the convergence $\varrho(F_n, F) \rightarrow 0$ as $n \rightarrow \infty$ it follows that there exists a subsequence $\{F_k\}$ of $\{F_n\}$ such that $\lim_{k \rightarrow \infty} h(F_k(t, x), F_0(t, x)) = 0$ for every $T > 0$ and a.e. $t \in [0, T]$, uniformly with respect to $x \in \mathbf{R}^n$. In virtue of Lemma 1, 1°, for every $T > 0$ we obtain

$$x_k(t_2; t_0, x_0) - x_k(t_1; t_0, x_0) \in \int_{t_1}^{t_2} F_k(s, x_k(s; t_0, x_0)) ds$$

for $t_1, t_2 \in [0, T], t_1 < t_2$ and $k \in \mathcal{N}$. Therefore

$$\|x_k(t_2; t_0, x_0) - x_k(t_1; t_0, x_0)\| \leq \int_{t_1}^{t_2} m(t) dt$$

Hence it follows that for any $T > 0$ there is a subsequence of $\{x_k(\cdot; t_0, x_0)\}$ uniformly converging on $[0, T]$, call it again $\{x_k(\cdot; t_0, x_0)\}$. Let $x_0(\cdot; t_0, x_0) = \lim_{k \rightarrow \infty} x_k(\cdot; t_0, x_0)$. Of course, we have $x_0(t_0; t_0, x_0) = x_0$.

It is not difficult to see that we can further select a subsequence of $\{x_k(\cdot; t_0, x_0)\}$, keeping notation $\{x_k(\cdot; t_0, x_0)\}$, such that $d(x_k(\cdot; t_0, x_0), x_0(\cdot; t_0, x_0)) \rightarrow 0$ as $k \rightarrow \infty$.

For every $T > 0$, $k \in \mathcal{N}$, and a.e. $t \in [0, T]$ we have

$$\alpha \left([x_0(t_2; t_0, x_0) - x_0(t_1; t_0, x_0)], \int_{t_1}^{t_2} F_0(s, x_0(s; t_0, x_0)) ds \right) \leq \|x_0(t_2; t_0, x_0) - x_k(t_2; t_0, x_0)\| + \|x_0(t_1; t_0, x_0) - x_k(t_1; t_0, x_0)\| + \int_0^T h(F_k(t, x_k(t; t_0, x_0)), F_0(t, x_0(t; t_0, x_0))) dt + \int_0^T h(F_0(t, x_k(t; t_0, x_0)), F_0(t, x_0(t; t_0, x_0))) dt$$

for $t_1, t_2 \in [0, T]$ and $t_1 < t_2$. Hence it follows that $\dot{x}_0(t; t_0, x_0) \in F_0(t, x_0(t; t_0, x_0))$ for a.e. $t \in [0, T]$, $T > 0$; i.e. $S(t_0, x_0, F_0) \neq \emptyset$.

In a similar way we obtain

LEMMA 3°. $\mathcal{P}(t_0, x_0, m, \varepsilon)$ is a closed subset of \mathcal{F} for each $\varepsilon > 0$, $t_0 \geq 0$, $x_0 \in \mathbf{R}^n$ and $m \in \bigcap_{T>0} \mathcal{L}_T^1$.

Let

$$\mathcal{R}(t_0, \varepsilon, \delta, m) = \bigcap_{x_0 \in B(0, \delta)} \mathcal{P}(t_0, x_0, m)$$

and let W^+ denote the set of all positive rational numbers. It is easy to prove that for every $t_0 \geq 0$ and $m \in \bigcap_{T>0} \mathcal{L}_T^1$

$$\bigcap_{\varepsilon>0} \bigcup_{\delta>0} \mathcal{R}(t_0, \varepsilon, \delta, m) = \bigcap_{\sigma \in W^+} \bigcup_{\delta \in W^+} \mathcal{R}(t_0, \varepsilon, \delta, m).$$

Hence and by Lemma 2° we obtain:

THEOREM 1°. The set \mathcal{A} of all $F \in \mathcal{F}_0$ for which the trivial solution $x_F \equiv 0$ of (1) is almost weakly stable is an $F_{\sigma\delta\sigma}$ set in (\mathcal{F}, ρ) .

THEOREM 2°. The set β of all $F \in \mathcal{F}_0$ for which the trivial solution $x_F \equiv 0$ of (1) is almost weakly unstable is a $G_{\delta\sigma\delta}$ set in (\mathcal{F}, ρ) .

References

- [1] H. A. Antosiewicz, A. Cellina, *Continuous selections and differential relations*, J. Diff. Equ. 19 (1975), p. 386-398.
- [2] A. Cellina, *Multivalued differential equations and ordinary differential equations*, SJAM, J. Appl. Math. 18 (1970), p. 533-538.

- [3] N. Kikuchi, *On control problems for functional-differential equations*, Funkc. Ekvac. 14 (1971), p. 1–23.
- [4] M. Kisielewicz, *Description of a class of differential equations with setvalued solutions I*, Atti Accad. Naz. Lincei 7 (1975), p. 158–162.
- [5] P. Krbeč, *Weak stability of multivalued differential equations*, Czech. Math. J. 26 (101) (1977), p. 470–476.

Reçu par la Rédaction le 9. 11. 1977
