On a mixed-type interpolation problem for real polynomials

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Abstract. Based on a result about weighted integral interpolation an existence and uniqueness theorem is established for real polynomials of degree (n+k+1) given k extremal points and n extremal values.

Introduction. Along with the classical interpolation problem for real polynomials passing through a given number of points on the real line a different kind of interpolation was studied by several authors namely the existence and uniqueness of real polynomials of degree n determined by (n-1) extremal values. This kind of interpolation was applied by Paszkowski [6] to determine disjoint intervals containing the Tchebysheff alternant points of polynomials of best uniform approximation to a continuous function on an interval.

This type of interpolation was also studied by Mycielski and Pasz-kowski in [5] and by Kuhn [3]. They obtained the following results.

THEOREM A [5]. Given (n+1) positive real numbers w_0, w_1, \ldots, w_n there exists one and only one polynomial p of degree n with real coefficients for which there are numbers $-1 = v_0 < v_1 < \ldots < v_n = 1$ such that $p(v_k) = (-1)^{n-k} w_k$ $(k = 0, 1, \ldots, n)$ and $p'(v_l) = 0$ $(l = 1, \ldots, n-1)$.

THEOREM B [3]. Given (n+1) real numbers $y_0, y_1, ..., y_n$ such that $(-1)^{n-j+1}(y_j-y_{j-1})>0$ (j=1,2,...,n) there exists a unique polynomial of degree (n+2) with leading coefficient 1, which takes (in order of increasing x) the extremal values $y_0, y_1, ..., y_n$ starting with y_0 at the origin.

In proving Theorem A the authors apply a topological method based on the properties of covering spaces studied by Browder ([1], Theorems 4-7) and Lelek and Mycielski [4]. We quote the result of [4] convenient for application in the interpolation problem discussed here.

THEOREM C. Let F be a continuous mapping of the n-dimensional sphere S^n into itself such that $F(S^n - \{p\}) \subset S^n - \{p\}$, F(p) = p for some $p \in S^n$. If the

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mapping $F|_{S^{n}-\{p\}}$ is a local homeomorphism, then F is a homeomorphism of S^{n} onto S^{n} .

On the other hand to establish Theorem B the author uses some properties from the theory of existence, uniqueness and continuability of solutions of normal differential systems of equations.

In this note we shall refer only to Theorem B since a straightforward argument shows that this theorem is stronger than Theorem A. In turn Theorem B is equivalent to the following ([3], Theorem 2)

THEOREM B'. Given n positive numbers F_1 , F_2 , ..., F_n there exists a unique polynomial of the form $p(x) = \prod_{k=0}^{n} (x-x_k)$, where $0 = x_0 < x_1 < ... < x_n$, such that

$$\int_{x_{j-1}}^{x_j} p(x) dx = (-1)^{n-j+1} F_j, \quad j = 1, 2, ..., n.$$

In this note we generalize Theorem B' by considering positive continuous weight functions. In particular we establish an existence and uniqueness result concerning a mixed-type interpolation problem whereby a fixed number of extremal points and of extreme values are a priori assigned. The method of proof will be based on a topological argument as in [5] which simplifies the proof as compared with the method used in [3] to prove Theorems B and B'.

Finally we remark that the complex plane counterpart of the problems cited above was studied in a series of papers by Charzyński and Kozłowski [2].

2. Two lemmas.

LEMMA 1. Let

$$a_{jk} = \int_{x_{j-1}}^{x_j} f(x)(x-x_0) \dots (x-x_{k-1})(x-x_{k+1}) \dots (x-x_n) dx,$$

where $1 \le j$, $k \le n$, $x_0 < x_1 < ... < x_n$ and f(x) is a continuous function of constant sign defined on (x_0, x_n) . Then

$$\Delta = \det(a_{ik}) \neq 0.$$

Proof. Adding row 1 to row 2, row 2 to row 3, ..., row (n-1) to row n, we may assume that the determinant in question has elements

$$b_{jk} = \int_{x_0}^{x_j} f(x)(x-x_0) \dots (x-x_{k-1})(x-x_{k+1}) \dots (x-x_n) dx, \quad 1 \leq j, k \leq n.$$

Keeping the last column fixed substract from the columns $1, \ldots, (n-1)$ the *n*-th column. This enables to factor $(x_1 - x_n)$ $(x_2 - x_n)$ \ldots $(x_{n-1} - x_n)$. Then

keeping the last two columns, (n-1) and n fixed, substract the (n-1)-th column from the columns $1, \ldots, (n-2)$. This enables to factor $(x_1 - x_{n-1}) \ldots (x_{n-2} - x_{n-1})$. Then keeping the last three columns fixed continue the process until the (n-1) last columns are kept fixed and column 2 is substracted from column 1, thus factoring $(x_1 - x_2)$. This leads to consideration of the determinant whose elements are

(1)
$$c_{jk} = \int_{x_0}^{x_j} f(x)(x-x_0)(x-x_1)\dots(x-x_{k-1}) dx,$$

 $1 \le j, k \le n$. Denote the determinant of the matrix (1) by $\Delta_n(x_n)$ to emphasize the dependence on n and x_n .

Obviously by hypothesis

$$\Delta_1(x_1) = \int_{x_0}^{x_1} f(x)(x - x_0) dx \neq 0$$

and

$$\Delta_{2}(x_{2}) = \begin{bmatrix} x_{1} & x_{1} & x_{1} \\ \int f(x)(x-x_{0}) dx & \int f(x)(x-x_{0})(x-x_{1}) dx \\ x_{0} & x_{2} & x_{2} \\ \int f(x)(x-x_{0}) dx & \int f(x)(x-x_{0})(x-x_{1}) dx \end{bmatrix}.$$

If $\Delta_2(x_2) = 0$, then since $\Delta_2(x_1) = 0$ it would follow that $\Delta'_2(\bar{x}_2) = 0$ for some $\bar{x}_2 \in (x_1, x_2)$. A short calculation shows that

$$\Delta_2'(\bar{x}_2) = f(\bar{x}_2)(\bar{x}_2 - x_0) \int_{x_0}^{x_1} f(x)(x - x_0)(\bar{x}_2 - x) dx$$

and we obtain a contradiction. Now assume by induction that Lemma 1 holds for determinants of the form (1) up to order (m-1), $1 \le m-1 \le n-1$. In particular $\Delta_{m-1}(x_{m-1}) \ne 0$. Denote by $\Delta_m(t)$ the expression $\Delta_m(x_m)$ in which t substitutes for x_m . If $\Delta_m(x_m) = 0$, then since $\Delta_m(x_{m-1}) = 0$ we would have $\Delta'_m(\bar{x}_m) = 0$ for some $\bar{x}_m \in (x_{m-1}, x_m)$. Differentiating $\Delta_m(t)$ with respect to t and in the resulting determinant multiplying column (m-1) by $(t-x_{m-1})$ and substracting from column m, column (m-2) multiplied by $(t-x_{m-2})$ substracting from column (m-1), ..., multiplying column 1 by $(t-x_1)$ and substracting from column 2, we obtain the relation

$$\Delta'_{m}(t) = (-1)^{m-1} f(t)(t - x_{0}) \det(d_{kl}),$$

where

$$d_{kl} = \int_{x_0}^{x_k} f(x)(x-t)(x-x_0)(x-x_1) \dots (x-x_{l-1}) dx,$$

 $1 \le k, l \le m-1$. It remains to apply the induction hypothesis with the function f(x) substituted by $f(x)(x-\bar{x}_m)$ and the interval (x_0, x_{m-1}) to obtained a contradiction to the relation $\Delta'_m(\bar{x}_m) = 0$.

In the case where f(x) is a constant the determinant Δ was evaluated in closed form in [3].

LEMMA 2. Let f(x) be a function defined for x > 0, integrable on every finite interval and such that $f(x) \ge m > 0$ for some positive constant m and x > 0. For given n distinct positive reals $x_1 < x_2 < ... < x_n$ define n numbers $A_1, A_2, ..., A_n$ by the formulas

(2)
$$A_j = (-1)^{n-j+1} \int_{x_{j-1}}^{x_j} f(x) p(x) dx, \quad j = 1, 2, ..., n,$$

where $x_0 = 0$ and $p(x) = \prod_{k=0}^{n} (x - x_k)$. Then if

$$\alpha_n = \min_{1 \le j \le n} (x_j - x_{j-1}, x_n^{-1}) \to 0$$
 also $\beta_n = \min_{1 \le j \le n} (A_j, A_j^{-1}) \to 0$.

Proof. One verifies that $\beta_n > 0$. We show that there exists a positive function h(d) defined for d > 0, $h(d) \to 0$ as $d \to 0$, such that $\beta_n \ge h$ implies $\alpha_n \ge d^{2n+4}$ for all sufficiently small positive d. Indeed in this case we have $h \le A_j \le h^{-1}$. Therefore by (2) choosing an interval $(x_{\mu-1}, x_{\mu})$ such that $x_{\mu} - x_{\mu-1} \ge x_{\mu}/n$ we have

$$h^{-1} \ge m \int_{x_{\mu-1}}^{x_{\mu}} (x - x_{\mu-1})^{\mu} (x_{\mu} - x)^{n-\mu+1} dx$$

$$= m(x_{\mu} - x_{\mu-1})^{n+2} \frac{\mu! (n - \mu + 1)!}{(n+2)!} \ge m \frac{x_n^{n+2}}{n^{n+2} (n+2)!}.$$

Hence

$$(3) x_n \leqslant ch^{-1/(n+2)},$$

where c is a positive constant which depends only on n and m. Furthermore for $1 \le j \le n$

(4)
$$h \leqslant \int_{x_{j-1}}^{x_j} f(x) |p(x)| dx \leqslant x_n^n (x_j - x_{j-1}) \int_0^{x_n} f(x) dx.$$

For t > 0 let $\varphi(t) = \int_0^t f(x) dx$ and let $\psi = \varphi^{-1}$. For d > 0 define $h(d) = c^{n+2} (\psi(d^{-1}))^{-(n+2)}$ or $d = (\varphi(ch^{-1/(n+2)}))^{-1}$. By hypothesis on f, $\varphi(t) \to \infty$ as $t \to \infty$ and thus $\psi(s) \to \infty$ as $s \to \infty$ and hence $h(d) \to 0$ as $d \to 0$. We now have by (4) and (3)

(5)
$$x_{j} - x_{j-1} \ge h x_{n}^{-n} \left(\int_{0}^{x_{n}} f(x) dx \right)^{-1}$$

$$\ge c^{-n} h^{(2n+2)/(n+2)} \left(\varphi(ch^{-1/(n+2)}) \right)^{-1} = c^{-n} h^{(2n+2)/(n+2)} d.$$

Now since $\varphi(t) \ge mt$, $\psi(t) \le t/m$ for t > 0.

Therefore (3) implies

(6)
$$x_n^{-1} \ge c^{-1} h^{1/(n+2)} = (\psi(d^{-1}))^{-1} \ge md \ge d^{2n+4}$$

for all sufficiently small positive d.

Also since $\psi(d^{-1}) \leq d^{-1}/m$ we have

(7)
$$h(d) = c^{n+2} (\psi(d^{-1}))^{-(n+2)} \geqslant c^{n+2} m^{n+2} d^{n+2}$$

By (5) and (7)

(8)
$$x_i - x_{i-1} \ge c^{n+2} m^{2n+2} d^{2n+3} \ge d^{2n+4}$$

for all sufficiently small positive d.

By (6) and (8) $\alpha_n \ge d^{2n+4}$ for all sufficiently small positive d. As a result we have established that $\alpha_n < d^{2n+4}$ implies $\beta_n < h(d)$ for sufficiently small positive d and $h(d) \to 0$ as $d \to 0$. This completes the proof of Lemma 2.

3. The Main Theorems.

THEOREM 1. Let f(x) be a continuous positive function defined on the positive real axis such that xf(x) is integrable near the origin. Assume that f(x) is bounded away from zero. For any n $(n \ge 1)$ positive numbers A_1, A_2, \ldots, A_n there exists a unique polynomial $p(x) = \prod_{k=0}^{n} (x-x_k), \ 0 = x_0 < x_1 < \ldots < x_n$ such that

(9)
$$\int_{x_{j-1}}^{x_j} p(x)f(x)dx = (-1)^{n-j+1}A_j, \quad j = 1, 2, ..., n.$$

Proof. Denote by P the subset of \mathbb{R}^n consisting of all points $(y_1, y_2, ..., y_n) \in \mathbb{R}^n$ such that $0 < y_1 < y_2 < ... < y_n$. Let $Q \supset P$ be the set of all points $(z_1, z_2, ..., z_n) \in \mathbb{R}^n$ such that $z_i > 0$, i = 1, 2, ..., n.

Define a mapping $\varphi: P \to Q$ as follows: For a point $x = (x_1, x_2, ..., x_n) \in P$ construct the polynomial of degree (n+1), $p(x) = \prod_{k=0}^{n} (x-x_k)$, where $x_0 = 0$ and define numbers

$$A_j = (-1)^{n-j+1} \int_{x_{j-1}}^{x_j} p(x)f(x)dx, \quad j=1, 2, ..., n.$$

One verifies easily that $A = (A_1, A_2, ..., A_n) \in Q$. Define the mapping φ by setting $\varphi(x) = A$. Since both P and Q are homeomorphic to \mathbb{R}^n we can

consider φ to be a mapping from S^n to S^n by adjoining points x_P and x_Q to P and Q, respectively, with the one point compactification topology and letting $\varphi(\infty_P) = \infty_Q$. By Lemma 1, φ is a local homeomorphism on $S^n - \{\infty_P\}$. By Lemma 2, φ is continuous at the point ∞_P . Therefore all conditions of Theorem C are satisfied and φ is a homeomorphism of S^n onto S^n and, in particular, of P onto Q. This implies Theorem 1.

As a consequence of Theorem 1 we obtain the following result concerning the mixed-type interpolation problem:

THEOREM 2. Let the k points $(k \ge 0)$

$$x_{-k} \leq x_{-k+1} \leq \ldots \leq x_{-1} < 0$$

and the n values $y_0, y_1, ..., y_{n-1}$ which satisfy $(-1)^{n-j} (y_j - y_{j-1}) > 0$ be given (j = 1, 2, ..., n-1). There exists a unique monic polynomial of degree (n+k+1), Q(x), which has the extreme points $x_{-k}, x_{-k+1}, ..., x_{-1}$ and has the extreme values $y_0, y_1, ..., y_{n-1}$ taken according to increasing values on the x-axis starting with y_0 at the origin.

Proof. Define

$$A_j = (-1)^{n-j} \frac{y_j - y_{j-1}}{n+k+1}, \quad j = 1, 2, ..., n-1.$$

By Theorem 1 with $f(x) = \prod_{i=1}^{k} (x - x_{-i})$, there exists a unique polynomial

$$p(x) = \prod_{l=0}^{n-1} (x - x_l) \text{ such that}$$

$$\int_{x_{j-1}}^{x_j} p(x) f(x) dx = (-1)^{n-j} A_j,$$

$$j = 1, 2, ..., n-1, 0 = x_0 < x_1 < ... < x_{n-1}.$$

Let

$$Q(x) = (n+k+1) \int_{x_0}^{x} p(x) f(x) dx + y_0.$$

Then Q(x) is a monic polynomial of degree (n+k+1) which satisfies $Q(x_j) = y_j$, j = 0, 1, ..., (n-1) and $Q'(x_{-i}) = Q'(x_j) = 0$, i = 1, 2, ..., k; j = 0, 1, ..., n-1.

With regards to the uniqueness of Q(x) one notices that if Q(x) has the required properties by Theorem 2, then Theorem 1 implies that the points $x_0, x_1, \ldots, x_{n-1}$ are uniquely determined. Hence the zeros of Q'(x) as well as its leading coefficient are uniquely determined. Therefore Q'(x) and thus Q(x) are uniquely determined. For k = 0, Theorem 2 reduces to Theorem B.

Remark. The requirement on f(x) to be bounded away from zero cannot be entirely dispensed with. It is easy to give an example with n = 1,

 $f(t) = O(t^{-4})$ for large t such that the problem discussed in Theorem 1 has no solution.

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