

An immersion of a differential space in a Cartesian space

by HANNA MATUSZCZYKOWA (Wrocław) and
WŁODZIMIERZ WALISZEWSKI (Łódź)

Abstract. For an arbitrary set A , the set \mathbf{R}^A of all real functions defined on A can be considered in a natural way as a differential space. The concept of a differential space has been introduced by R. Sikorski [2] and, independently, by S. Mac Lane [1]. In the present paper we prove that an arbitrary differential space can be induced from the natural differential space of the set \mathbf{R}^A , and in the case when the differential structure separates points it can be immersed in \mathbf{R}^A .

1. The natural structure of the set \mathbf{R}^A . For every $a \in A$ and for every function x of \mathbf{R}^A we set $\hat{a}(x) = x(a)$. Then we have the projection

$$(1) \quad \hat{a}: \mathbf{R}^A \rightarrow \mathbf{R}.$$

The set \mathbf{R} of all reals has the natural differential structure $C^\infty(\mathbf{R})$ consisting of all infinitely many differentiable real functions on \mathbf{R} . The smallest differential structure $\mathbf{R}(A)$ on the set \mathbf{R}^A , for which all projections of the form (1), $a \in A$, are smooth will be called the *natural differential structure of the set \mathbf{R}^A* . For any set C of real functions defined on a set M , let C be the set of all real functions of the form

$$\omega(a_1(\cdot), \dots, a_s(\cdot)),$$

where a_1, \dots, a_s are elements of C , ω is any infinitely differentiable real function on \mathbf{R}^s , s is an arbitrary positive integer. In general, by C_M we denote the set of all functions $\beta: M \rightarrow \mathbf{R}$ such that for every p of M there exist $a \in C$ and a set U such that $\beta|U = a|U$, U is open in the weakest topology τ_C on the set M for which all functions of C are continuous. For an arbitrary mapping $f: M \rightarrow N$ we define the mapping $f^*: \mathbf{R}^N \rightarrow \mathbf{R}^M$ by the formula: $f^*(\beta) = \beta \circ f$ for $\beta \in \mathbf{R}^N$ (see [4]).

We have $\hat{a}: \mathbf{R}^A \rightarrow \mathbf{R}$. Then

$$\hat{a}^*: \mathbf{R}^{\mathbf{R}} \rightarrow \mathbf{R}^{(\mathbf{R}^A)}$$

is the mapping defined by $\hat{a}^*(\gamma) = \gamma \circ \hat{a}$, where $\gamma: \mathbf{R}^{\mathbf{R}} \rightarrow \mathbf{R}$. We mean by $\hat{a}^*[C^\infty(\mathbf{R})]$ the set of all functions $\gamma \circ \hat{a}$, where $\gamma \in C^\infty(\mathbf{R})$. Then we

have

$$(2) \quad \mathbf{R}(A) = \left(\text{sc} \bigcup_{a \in A} \hat{a}^* [C^\infty(\mathbf{R})] \right)_{\mathbf{R}^A}.$$

We will prove

1.1. *The structure $\mathbf{R}(A)$ defined by (2) is the unique differential structure on the set \mathbf{R}^A such that for every differential space (M, C) and for every function $f: M \rightarrow \mathbf{R}^A$ the mapping*

$$(3) \quad f: (M, C) \rightarrow (\mathbf{R}^A, \mathbf{R}(A))$$

is smooth iff all mappings

$$(4) \quad \hat{a} \circ f: (M, C) \rightarrow (\mathbf{R}, C^\infty(\mathbf{R}))$$

are smooth for $a \in A$.

Proof. Assume that we have smooth mappings (4), $a \in A$. Let $\beta \in \bigcup_{a \in A} \hat{a}^* [C^\infty(\mathbf{R})]$. Then $\beta \in \hat{a}^* [C^\infty(\mathbf{R})]$ for some $a \in A$. Therefore, $\beta = \gamma \circ \hat{a}$, where $\gamma \in C^\infty(\mathbf{R})$. Hence it follows that $\beta \circ f = \gamma \circ (\hat{a} \circ f) \in C$. Thus, the mapping (3) is smooth (see [4]).

Now, suppose that D is a differential structure on \mathbf{R}^A such that for any $f: M \rightarrow \mathbf{R}^A$ the mapping

$$(5) \quad f: (M, C) \rightarrow (\mathbf{R}^A, D)$$

is smooth iff all mappings (4) are smooth for $a \in A$. We have to prove that $D = \mathbf{R}(A)$. The mapping (5) is smooth iff the mapping (3) is smooth. Setting $f = \text{id}$ and $M = \mathbf{R}^A$ we have the smooth mapping

$$\text{id}: (\mathbf{R}^A, \mathbf{R}(A)) \rightarrow (\mathbf{R}^A, \mathbf{R}(A)).$$

Hence we get the smooth mapping

$$\text{id}: (\mathbf{R}^A, \mathbf{R}(A)) \rightarrow (\mathbf{R}^A, D).$$

Then $D \subset \mathbf{R}(A)$. Similarly, the smoothness of $\text{id}: (\mathbf{R}^A, D) \rightarrow (\mathbf{R}^A, D)$ yields that the mapping

$$\text{id}: (\mathbf{R}^A, D) \rightarrow (\mathbf{R}^A, \mathbf{R}(A))$$

is smooth. Consequently, we have the inclusion $\mathbf{R}(A) \subset D$.

1.2. *If $\text{card} A = \text{card} B$, then the differential spaces $(\mathbf{R}^A, \mathbf{R}(A))$ and $(\mathbf{R}^B, \mathbf{R}(B))$ are diffeomorphic. More exactly, if φ is a one-to-one mapping A onto B , then the mapping $\varphi^*: \mathbf{R}^B \rightarrow \mathbf{R}^A$ gives a diffeomorphism $(\mathbf{R}^B, \mathbf{R}(B))$ onto $(\mathbf{R}^A, \mathbf{R}(A))$.*

Proof. Suppose $\varphi: A \rightarrow B$ is one-to-one. Then $\varphi^*: \mathbf{R}^B \rightarrow \mathbf{R}^A$ is one-to-one. Let $\beta \in \hat{a}^* [C^\infty(\mathbf{R})]$, where $a \in A$. Thus $\beta = \hat{a}^*(\gamma)$, $\gamma \in C^\infty(\mathbf{R})$. Hence it follows $\beta \circ \varphi^* = \hat{a}^*(\gamma) \circ \varphi^* = \gamma \circ \hat{a} \circ \varphi^* = \gamma \circ \hat{b} = \hat{b}^*(\gamma) \in \hat{b}^* [C^\infty(\mathbf{R})]$, where $b = \varphi(a)$, $\hat{b}(y) = y(b)$ for $y \in \mathbf{R}^B$. Therefore, $\beta \circ \varphi^* \in \mathbf{R}(B)$ when

$\beta \in \bigcup_{a \in A} \hat{a}^*[C^\infty(\mathbf{R})]$. Then we have the smooth mapping

$$(6) \quad \varphi^*: (\mathbf{R}^B, \mathbf{R}(B)) \rightarrow (\mathbf{R}^A, \mathbf{R}(A)).$$

Similarly, we prove that the mapping inverse to (6) is smooth.

Now, for any cardinal n we define the n -th power of \mathbf{R} , \mathbf{R}^n , as a differential space of the form $(\mathbf{R}^A, \mathbf{R}(A))$, where A is the set of all ordinals less than ν , ν being the smallest ordinal of cardinality n . From 1.2 it follows that every differential space $(\mathbf{R}^B, \mathbf{R}(B))$, where $\text{card } B = n$, is diffeomorphic to \mathbf{R}^n .

2. The inducing of a differential space from \mathbf{R}^n . Let (M, C) be any differential space and let $n = \text{card } C$. For every $p \in M$, $i(p)$ denotes the function defined by the formula

$$(7) \quad i(p)(a) = a(p) \quad \text{for } a \in C.$$

We have the mapping

$$(8) \quad i: M \rightarrow \mathbf{R}^C.$$

We will make use of the concept of the differential space induced by a mapping, which has introduced in [4]. First we prove the lemma:

2.1. *The differential space induced from $(\mathbf{R}^C, \mathbf{R}(C))$ by the mapping (8) coincides with (M, C) .*

Proof. Let us denote by \tilde{C} the differential structure induced from $(\mathbf{R}^C, \mathbf{R}(C))$ by (8). We have (see [4]) $\tilde{C} = (\text{sci}^*[\mathbf{R}(C)])_M$. We will prove that $\tilde{C} = C$. It is easy to see that $C \subset \tilde{C}$ and that the weakest topology $\tau_{\tilde{C}}$ for which all functions of \tilde{C} are continuous consists of the counter-images of the members of the topology $\tau_{\mathbf{R}(C)}$ under mapping (8). In other words, a set is open in $\tau_{\tilde{C}}$ iff it is of the form $i^{-1}[U]$, where U is open in $\tau_{\mathbf{R}(C)}$. We set

$$C_0 = \bigcup_{a \in C} \hat{a}^*[C^\infty(\mathbf{R})].$$

Then we have (see [4]) $\tau_{\mathbf{R}(C)} = \tau_{C_0}$. We will prove that the topology τ_{C_0} coincides with the Tichonov topology of the product

$$(9) \quad \prod_{a \in C} \mathbf{R}_a,$$

where, for each $a \in C$, \mathbf{R}_a denotes the set \mathbf{R} with the natural topology. Indeed, for any $a \in C$, any reals $a < b$ and for every real function $\beta \in \hat{a}^*[C^\infty(\mathbf{R})]$ we have

$$\beta^{-1}[(a; b)] = \hat{a}^{-1}[\gamma^{-1}[(a; b)]],$$

where $\gamma \in C^\infty(\mathbf{R})$. A subbase of the topology τ_{C_0} is then contained in the set of all sets of the form $\hat{a}^{-1}[H]$, where H is an open subset of \mathbf{R} , a is an arbitrary function of C . Thus, this subbase is contained in the Tichonov

topology of product (9). Now, let us take any set of the form $\hat{a}^{-1}[(a; b)]$, where $a < b$ and $a \in C$. Then we have

$$\hat{a}^{-1}[(a; b)] = (\hat{a}^*(\text{id}_{\mathbf{R}}))^{-1}[(a; b)],$$

$\hat{a}^*(\text{id}_{\mathbf{R}}) \in C_0$. Therefore, the subbase of the topology of the product (9) is contained in τ_{C_0} . Consequently these topologies coincide.

To prove the inclusion $\tilde{C} \subset C$, let us take any $a \in i^*[\mathbf{R}(C)]$. Then $a = \gamma \circ i$, $\gamma \in \mathbf{R}(C)$. Let $p \in M$. Then $i(p) \in \mathbf{R}^C$. There exists $U \in \tau_{C_0}$ such that $i(p) \in U$ and $\gamma|U = \gamma_0|U$, where $\gamma_0 \in \text{sc}C_0$. Therefore, for some $\gamma_1, \dots, \gamma_s \in C_0$, $\gamma_0 = \omega(\gamma_1(\cdot), \dots, \gamma_s(\cdot))$, where $\omega \in C^\infty(\mathbf{R}^s)$. There exist $a_1, \dots, a_s \in C$ such that $\gamma_j \in \hat{a}_j^*[C^\infty(\mathbf{R})]$, $j = 1, \dots, s$.

Thus, $\gamma_j = \hat{a}_j^*(\eta_j) = \eta_j \circ \hat{a}_j$, where $\eta_j \in C^\infty(\mathbf{R})$. For any $x \in \mathbf{R}^C$ we get

$$\gamma_0(x) = \omega(\eta_1(\hat{a}_1(x)), \dots, \eta_s(\hat{a}_s(x))) = \theta(x(a_1), \dots, x(a_s)),$$

where $\theta(u^1, \dots, u^s) = \omega(\eta_1(u^1), \dots, \eta_s(u^s))$ for $(u^1, \dots, u^s) \in \mathbf{R}^s$. Thus we have

$$\begin{aligned} a(q) &= i^*(\gamma)(q) = (\gamma \circ i)(q) = \gamma(i(q)) = \gamma_0(i(q)) \\ &= \theta(i(q)(a_1), \dots, i(q)(a_s)) = \theta(a_1(q), \dots, a_s(q)) \end{aligned}$$

for $q \in i^{-1}[U]$.

The set U being open in the topology of the product (9) is of the form $\bigtimes_{\delta \in C} U_\delta$, where the sets U_δ are open in \mathbf{R} and there are only finitely many $\delta \in C$ for which $U_\delta \neq \mathbf{R}$. Call then $\delta_1, \dots, \delta_r$. Then we get

$$p \in i^{-1}[U] = \bigcap_{h=1}^r \delta_h^{-1}[U_{\delta_h}] \in \tau_C.$$

The function $\theta(a_1(\cdot), \dots, a_s(\cdot))$ belongs to C . Hence it follows that $a \in C_M = C$.

As a corollary we get the following theorem.

2.2. *Every differential space has a differential structure induced from \mathbf{R}^n , n being a suitable cardinal, by some mapping. If the topology of the differential space is Hausdorff, we may require this mapping to be one-to-one.*

References

- [1] S. MacLane, *Differentiable spaces*, Notes for Geometrical Mechanics, Winter 1970, p. 1-9.
- [2] R. Sikorski, *Abstract covariant derivative*, Colloq. Math. 18 (1967), p. 251-272.
- [3] — *Wstęp do geometrii różniczkowej* (Polish), Warszawa 1972.
- [4] W. Waliszewski, *Regular and coregular mappings of differential spaces*, Ann. Polon. Math. 30 (1975), p. 263-281.

Reçu par la Rédaction le 28. 4. 1976