

Remark on a conjectured characterization of the sphere

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Abstract. It is proved that a convex body in a three-dimensional Euclidean space whose surface area measures Φ_1, Φ_2 satisfy the inequality $\Phi_2 - 2r\Phi_1 + r^2\Omega \leq 0$ (Ω being Lebesgue measure on the unit sphere) with some constant r , and which admits some circular projection, is either a ball or a solid circular cylinder with two half-balls attached to its ends. This generalizes (and simplifies the proof of) a recent result of Koutroufiotis who considered ovaloids of class C^3 with positive Gauss curvature.

It has been conjectured that a sufficiently smooth ovaloid (closed convex surface) in a three-dimensional Euclidean space E^3 , whose principal curvatures k_1, k_2 satisfy the inequality

$$(1) \quad (k_1 - c)(k_2 - c) \leq 0$$

with some constant c , must be a sphere. Partial results have been obtained by Aleksandrov [2] (for analytic surfaces and under the additional assumption that $(k_1 - c)(k_2 - c) = 0$ only if both factors are zero), and Münzner [9] (for analytic surfaces) and [8] (for surfaces of revolution). Recently Koutroufiotis [7] has shown that an ovaloid of class C^3 with positive Gauss curvature is necessarily a sphere if (1) holds and if the surface is assumed to admit a circular enveloping cylinder in some direction. The purpose of this note is to show that, if this additional hypothesis is accepted, a very short proof is possible, and a more general result can be obtained.

For an ovaloid with positive Gauss curvature assumption (1) is equivalent to

$$(2) \quad S_2 - 2rS_1 + r^2 \leq 0,$$

where $r = c^{-1}$ and $S_2, 2S_1$ denote the product, respectively the sum, of the principal radii of curvature of the surface. Here S_2, S_1 are viewed as functions on the unit sphere Σ with its centre at the origin of E^3 , where the correspondence between the ovaloid and the sphere is established by the spherical image map. For a unit vector $v \in \Sigma$ we have the well-known

formulae (Bonnesen–Fenchel [3], p. 67)

$$(3) \quad \begin{aligned} \int_{\Sigma} |\langle u, v \rangle| S_2(u) d\Omega(u) &= 2A(v), \\ \int_{\Sigma} |\langle u, v \rangle| S_1(u) d\Omega(u) &= L(v) \end{aligned}$$

($\langle \cdot, \cdot \rangle$ being the inner product in E^3 and Ω Lebesgue measure on Σ), where $A(v)$ denotes the area of the orthogonal projection of the ovaloid in direction v onto some plane, and $L(v)$ is the length of the boundary curve of that projection. If now the enveloping cylinder of the ovaloid in direction v is circular, say of radius ϱ , it follows from (2) and (3) that

$$0 \geq \int_{\Sigma} |\langle u, v \rangle| (S_2 - 2rS_1 + r^2) d\Omega(u) = 2\pi(\varrho - r)^2 \geq 0,$$

hence $\varrho = r$, and the surface satisfies $S_2 - 2rS_1 + r^2 = 0$, or $(k_1 - c)(k_2 - c) = 0$ throughout. In this case it is well known that the ovaloid must be a sphere.

Let us now turn to the announced generalization. It concerns arbitrary convex bodies. For a convex body K (non-empty, compact, convex point set) in E^3 , let $\Phi_2(K, \cdot)$ denote its second and $\Phi_1(K, \cdot)$ its first surface area measure, as introduced by Aleksandrov [1] (§ 2, p. 962 and 966) and Fenchel–Jessen [5] (see also Busemann [4], § 8 and p. 70). Thus Φ_2 and Φ_1 are Borel measures on the unit sphere Σ , which may be characterized by the fact that they depend in a weakly continuous manner on the convex bodies (where the set of convex bodies is equipped with the usual topology induced by the Hausdorff–Blaschke metric, see [3], p. 34), and that

$$\Phi_i(K, \omega) = \int_{\omega} S_i d\Omega \quad \text{for each Borel set } \omega \subseteq \Sigma$$

($i = 1, 2$), if the boundary of K is of class C^2 and has positive Gauss curvature. Hence, for such convex bodies, assumption (1) is equivalent to

$$(4) \quad \Phi_2(K, \cdot) - 2r\Phi_1(K, \cdot) + r^2\Omega \leq 0;$$

but the latter inequality makes sense for arbitrary convex bodies. We shall prove the following theorem.

THEOREM. *If a convex body K in E^3 satisfies (4) with some constant r and admits some circular orthogonal projection, then K is either a ball or a solid circular cylinder with two half-balls attached to its ends.*

It has been conjectured by A. D. Aleksandrov (in his lecture at the ICM, Moscow 1966) that this result holds without the assumption on the existence of a circular projection. Clearly our theorem implies the result of Koutroufiotis, since the boundary surface of the “telescoped” ball is only C^1 .

To prove the theorem, we first remark that formulae (3) hold for an arbitrary convex body, if $S_i d\Omega$ is replaced by $d\Phi_i$ (see, e.g., [1], II). Therefore assumption (4) implies that any circular projection of the body K has radius r , and that

$$(5) \quad \Phi_2(K, \omega) - 2r\Phi_1(K, \omega) + r^2\Omega(\omega) = 0$$

for each Borel set $\omega \subseteq \Sigma \setminus \sigma_v$, where $\sigma_v = \{u \in \Sigma \mid \langle u, v \rangle = 0\}$, provided that $v \in \Sigma$ is a direction for which the projection of K is circular. We shall show that (5) holds also for $\omega \subseteq \sigma_v$.

Let Z denote the cylindrical surface of direction v circumscribed about the body K . Thus the (orthogonal) cross-section of Z is a circle of radius r . Let B_r denote a ball of radius r inscribed into Z . Then each convex body $(1-\lambda)K + \lambda B_r$ (where $0 \leq \lambda \leq 1$) is also inscribed into Z . The geometrical interpretation of the measure Φ_2 tells us that $\Phi_2((1-\lambda) \times K + \lambda B_r, \sigma_v)$ is the surface area of $Z \cap [(1-\lambda)K + \lambda B_r]$. If G is any generating line of the cylinder Z , we have

$$G \cap [(1-\lambda)K + \lambda B_r] = (1-\lambda)(G \cap K) + \lambda(G \cap B_r)$$

(a consequence of [3], p. 31), from which we deduce that

$$(6) \quad \Phi_2((1-\lambda)K + \lambda B_r, \sigma_v) = (1-\lambda)\Phi_2(K, \sigma_v).$$

On the other hand, for an arbitrary Borel set $\omega \subseteq \Sigma$ the equality

$$(7) \quad \Phi_2((1-\lambda)K + \lambda B_r, \omega) = (1-\lambda)^2\Phi_2(K, \omega) + 2(1-\lambda)\lambda r\Phi_1(K, \omega) + \lambda^2 r^2 \Omega(\omega)$$

holds (a special case of [5], p. 23). Comparison of (6) and (7) yields $\Phi_2(K, \sigma_v) - 2r\Phi_1(K, \sigma_v) = 0$. As $\Omega(\sigma_v) = 0$ and (4) is assumed, we see that (5) is valid for each Borel subset ω of σ_v , and hence for arbitrary Borel sets on Σ . In particular, we may take Σ itself, which means that

$$(8) \quad F(K) - 2rM(K) + 4\pi r^2 = 0.$$

Here $F(K)$ denotes the surface area of K , and $M(K)$ is 2π times its mean width (or "integral of mean curvature").

Finally we consider the function f defined by

$$f(\lambda) = F((1-\lambda)K + \lambda B_r), \quad 0 \leq \lambda \leq 1.$$

As K and B_r are inscribed into the same cylinder, the function f is known to be concave (Hadwiger [6], p. 256 and 259). But from the well-known formula

$$f(\lambda) = (1-\lambda)^2 F(K) + 2(1-\lambda)\lambda r M(K) + 4\pi \lambda^2 r^2$$

and equality (8) we see that f is even linear. As Hadwiger (loc. cit.) has proved, this can only happen if there are numbers $\varrho, \sigma \geq 0$ and a segment S parallel to v such that $K + \varrho S$ is a translate of $B_r + \sigma S$. Clearly $\sigma \geq \varrho$, and K is a translate of $B_r + (\sigma - \varrho)S$.

Added in proof. That spheres are the only closed analytic surfaces which satisfy (1) has also been proved by A. D. Aleksandrov, *On the curvature of surfaces* (Russian), Vestnik Leningrad. Univ. 21, No. 19 (Ser. Mat. Meh. Astron. No. 4) (1966), p. 5–11.

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