

Characterizations of H_{x_1} -sufficiency of jets

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Abstract. The aim of this paper is to investigate germs of maps in manifolds with boundary. The main results are contained in Theorems 1, 2, 3.

1. Definitions and notation. Let R^n denote the Euclidean space of dimension n and $E(n, p)$ the set of all germs of maps $f: R^n \rightarrow R^p$, $f(0) = 0$, $J^r(n, p)$ is the space of jets.

DEFINITION 1. A homeomorphism $\sigma: R^n \rightarrow R^n$ is boundary preserving if

$$\sigma(\{0 \times R^{n-1}\}) \subset \{0 \times R^{n-1}\}.$$

The set of all homeomorphisms of R^n preserving boundaries will be denoted by H_{x_1} .

DEFINITION 2. An r -jet $w \in J^r(n, p)$ is called H_{x_1} -sufficient if for every $f: R^n \rightarrow R^p$, $f(0) = 0$, and $j^r(f) = w$ there exists $\sigma \in H_{x_1}$ such that $f_0 \sigma = w$.

Given $f: R^n \rightarrow R^p$, let us put

$$v_i^f = \left(x_1 \frac{\partial f_i}{\partial x_1}, \frac{\partial f_i}{\partial x_2}, \dots, \frac{\partial f_i}{\partial x_n} \right), \quad i = 1, \dots, p.$$

THEOREM 1. An r -jet $w \in J^r(n, p)$ is H_{x_1} -sufficient if there exist a positive number c and a neighbourhood U of 0 such that

$$(1) \quad d(v_1^w, \dots, v_p^w) \geq c|x|^{r-1}$$

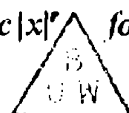
for every $x \in U$.

THEOREM 2. If $w \in J^r(n, p)$ is H_{x_1} -sufficient, then there exists a positive number c and a neighbourhood U of 0 such that

$$(2) \quad d(v_1^w, \dots, v_p^w) \geq c|x|^{r+1} \quad \text{for every } x \in U.$$

THEOREM 3. Let $w \in J^r(n, p)$. If there exist a positive number c and a neighbourhood U of 0 such that

$$(3) \quad d(\Phi_1, \dots, \Phi_p) \geq c|x|^r \quad \text{for every } x \in U,$$



then w is H_{x_i} -sufficient for every i , where

$$(4) \quad \Phi_i = \left(x_1 \frac{\partial w_i}{\partial x_1}, x_2 \frac{\partial w_i}{\partial x_2}, \dots, x_n \frac{\partial w_i}{\partial x_n} \right), \quad i = 1, \dots, p.$$

For manifolds without boundary, Bochnak [1] has shown that w is H_{x_1} -sufficient if and only if condition (1) is satisfied. The following example shows that for manifolds with boundary condition (1) is only sufficient and not necessary.

EXAMPLE. Let $w(x, y) = x^2 + y^2 \in J^2(2, 1)$. Then w is H_x - and H_y -sufficient.

2. Proof of Theorems 1, 2, 3.

2.1. Proof of Theorem 1. For every $f: (\mathbb{R}^n, 0) \rightarrow (\mathbb{R}^p, 0)$ and $f'(f) = w$, let us put

$$F(x, t) = w(x) + t(f(x) - w(x)) \quad \text{for } (x, t) \in \mathbb{R}^n \times \mathbb{R}$$

and

$$(2.1) \quad Y(x, t) = \sum_{i=1}^p ((0, 1) \cdot v_i^F) |N_i|^{-2} N_i = \sum_{i=1}^p (f_i - w_i) |N_i|^{-2} N_i,$$

where

$$v_i^F = \left(w_1 \frac{\partial F_i(x, t)}{\partial x_1}, \frac{\partial F_i(x, t)}{\partial x_2}, \dots, \frac{\partial F_i(x, t)}{\partial x_n}, \frac{\partial F_i(x, t)}{\partial t} \right)$$

and N_i is the projection of v_i^F onto the space orthogonal to the space spanned by $v_j^F(x_1, \dots, x_n, t)$ with $j \neq i$. $Y(x, t)$ is the projection of $(0, \dots, 0, 1)$ onto the subspace spanned by v_1^F, \dots, v_p^F .

Then

$$(2.2) \quad V(x, t) = (V_1, \dots, V_{n+1}) = (0, \dots, 0, 1) - Y(x, t)$$

is orthogonal to v_i^F for every i , i.e.,

$$x_1 \frac{\partial F_i}{\partial x_1} \cdot V_1 + \frac{\partial F_i}{\partial x_2} \cdot V_2 + \dots + \frac{\partial F_i}{\partial t} \cdot V_{n+1} = 0.$$

Write

$$(2.3) \quad X(x, t) = (x_1 V_1, V_2, \dots, V_{n+1}).$$

Then $X(x, t)$ is orthogonal to $(\partial F_i / \partial x_1, \dots, \partial F_i / \partial x_n, \partial F_i / \partial t)$, $i = 1, \dots, p$.

LEMMA 2.1 [2]. In the notation of Theorem 1, we have

$$d(v_1^F, \dots, v_p^F) \geq \frac{1}{2} c |x|^{r-1} \quad \text{for every } x \in U.$$

Let us consider the differential equation

$$(2.4) \quad \frac{dx}{d\tau} = X(x, t),$$

where $X(x, t)$ is a map from an open subset of $\mathbf{R}^n \times \mathbf{R}$ containing $B_\varepsilon^n \times [0, 1]$ into \mathbf{R}^{n+1} ,

$$B_\varepsilon^n = \{x \in \mathbf{R}^n : |x| \leq \varepsilon\}.$$

Let us note that $X(x, t)$ satisfies the following conditions:

- (i) $X(x, t)$ is continuous for every $(x, t) \in B_\varepsilon^n \times [0, 2] = A_\varepsilon$,
- (ii) $\lim_{x \rightarrow 0} \frac{|X(x, t) - X(x, 0)|}{|x|} = 0$ uniformly with respect to t ,
- (iii) $\langle X(x, t), l_{n+1} \rangle > 0$ for every $(x, t) \in A_\varepsilon$.

In fact, by Lemma 2.1 we have

$$|N_i| \geq d(v_1^f, \dots, v_p^f) \geq \frac{1}{2} c |x|^{r-1}, \quad i = 1, \dots, p.$$

This implies that

$$|Y(x, t)| \leq 2 \sum_{i=1}^p |f_i - w_i| \frac{1}{|N_i|} = o(|x|).$$

Hence $V(x, t)$ satisfies conditions (i)–(iii). Thus $X(x, t)$ does so. By [1], (2.4) has the unique solution $\eta(x, t; \tau)$ satisfying the condition $\eta(x, t, 0) = (x, t)$ and

- (a) $\tau \rightarrow \eta(x, t; \tau)$ is the unique solution of (2.4) satisfying the condition $\eta(x, t; 0) = (x, t)$ in a neighbourhood W of $B_\varepsilon^n \times [0, 1] \times \{0\} \subset \mathbf{R}^n \times \mathbf{R} \times \mathbf{R}$,
- (b) $\eta(0, 0; \tau) = (0, \tau)$,
- (c) $(\eta(\{x \times 0\} \times \mathbf{R})) \cap W \cap (\mathbf{R}^n \times \{1\})$ contains the point $(\sigma(x), 1)$,
- (d) F is constant on $\eta((x, t) \times \mathbf{R}) \cap W$.

From conditions (a)–(d) it follows that the map σ is a homeomorphism such that $f \circ \sigma = w$. It remains to show that $\sigma \in H_{x_1}$.

In fact,

$$X(x, t)|_{x=0} = (0, V_2, \dots, V_{n+1}) = X_1(x', t),$$

where $x' = (0, x_2, \dots, x_n)$

We have

$$\frac{\partial F_i(x', t)}{\partial x_2} \cdot V_2 + \dots + \frac{\partial F_i(x', t)}{\partial t} \cdot V_{n+1} = 0.$$

On the other hand, since $X(x, t)$ satisfies (i)–(iii), $X_1(x', t)$ does so. This implies that the equation

$$(2.5) \quad \frac{dx'}{d\tau} = X_1(x', t)$$

has the unique solution $\eta_*(x', t; \tau)$ satisfying the condition $\eta_*(x', t; 0) = (x', t)$.

By the continuity of $\eta(x, t; \tau)$ we infer that $\eta(x, t; \tau)|_{x_1=0}$ is a solution of (2.5).

Thus

$$(2.6) \quad \eta(x, t; \tau)|_{x_1=0} = \eta_*.$$

Since η_* induces a homeomorphism $\sigma_*: \mathbf{R}^{n-1} \rightarrow \mathbf{R}^{n-1}$, we have by (2.6) $\sigma|_{x_1=0} = \sigma_*$. Thus σ preserves the boundary.

2.2. Proof of Theorem 2. We first prove the following claim, under the hypothesis of Theorem 2:

(d_{x₁}) For every $f: U \rightarrow \mathbf{R}^p$, $f \in C^r$, and $f'(f) = w$ and for every sequence $\{a_i\}_{i \in \mathbf{N}} \subset \mathbf{R}^n$, $a_i \rightarrow 0$, $a_i \neq 0$, $f^{-1}(f(a_i))$ is a topological manifold with boundary of codimension p and the boundary of $f^{-1}(f(a_i))$ is the intersection of $f^{-1}(f(a_i))$ with the hyperspace $x_1 = 0$.

To prove (d_{x₁}), we need the following lemma, which is an immediate consequence of Lemma 1 [1].

LEMMA. Let U, V be open subsets of \mathbf{R}^k and \mathbf{R}^l , respectively, $F: U \times V \rightarrow \mathbf{R}^p$ be a C^∞ -map and B be a countable set of \mathbf{R}^p contained in the set of all regular values of F and $F|_{x_1} = 0$.

Then there exists a point $y_0 \in V$ such that B is contained in the set of regular values of both $F(x_1, \dots, x_k, y_0)$ and $F(0, x_2, \dots, x_k, y_0)$.

Applying this lemma we can prove (d_{x₁}).

Let $a_i \xrightarrow{i \rightarrow \infty} 0$, $a_i \in \mathbf{R}^n \setminus \{0\}$, and $f: \mathbf{R}^n \rightarrow \mathbf{R}^p$ be a C^r -map, with $f'(f) = w$.

Consider the map $\mathbf{R}^n \times \mathbf{R}^p \rightarrow \mathbf{R}^p$ defined by

$$F_j(x, y) = w_j(x) + y_j|x|^{2r}, \quad j = 1, 2, \dots, p;$$

obviously, $f(a_i)$ is a regular value of both $F(x, y)$ and $F(x, y)|_{x_1=0}$.

We now show that condition (d_{x₁}) implies Theorem 2.

Indeed, if it is not the case then there exists a sequence $\{a_i\}$; $a_i \neq 0$, $a_i \rightarrow 0$, such that

$$d\{v_1^w(a_i), \dots, v_p^w(a_i)\} = o(|a_i|^{r+1}).$$

Then by [1] there are linearly independent vectors $\lambda_1^i, \dots, \lambda_p^i$ satisfying the conditions:

- (a) The vectors $v_2^w(a_i) + \lambda_2^i, \dots, v_p^w(a_i) + \lambda_p^i$ are linearly independent.
- (b) $v_1^w(a_i) \in \text{Span}\{v_2^w(a_i) + \lambda_2^i, \dots, v_p^w(a_i) + \lambda_p^i\}$,
- (c) $|\lambda_k^i| = o(|a_i|^{r+1})$, $k = 2, \dots, p$.

Since $w(x)$ is H_{x_1} -sufficient, $w(x)|_{x_1=0}$ is H -sufficient in $\mathbf{R}^{n-1} = 0 \times \mathbf{R}^{n-1} \subset \mathbf{R}^n$.

Indeed; let $f: \mathbb{R}^{n-1} \rightarrow \mathbb{R}^p$ be a map with $J'(f) = w(x)|_{x_1=0}$.

Write $w(x_1, x_2, \dots, x_n)$ in the form

$$w(x_1, x_2, \dots, x_n) = w(x_1, x_2, \dots, x_n)|_{x_1=0} + x_1 \varphi(x_1, x_2, \dots, x_n).$$

Put $g = f(x_2, \dots, x_n) + x_1 \varphi(x_1, x_2, \dots, x_n)$. Then

$$J'(g) = J'(f) + J'(x_1 \varphi) = w|_{x_1=0} + J'(x_1 \varphi) = w.$$

Since w is H_{x_1} -sufficient, there exists $\sigma \in H_{x_1}$ such that

$$(2.7) \quad g \circ \sigma = w, \quad g \circ \sigma = f \circ \sigma + (x_1 \varphi) \circ \sigma.$$

From (2.6) we get

$$(2.8) \quad g \circ \sigma|_{x_1=0} = w(x_1, \dots, x_n)|_{x_1=0}.$$

By (2.7)

$$(2.9) \quad g \circ \sigma|_{x_1=0} = f \circ \sigma|_{x_1=0} + (x_1 \varphi) \circ \sigma|_{x_1=0} = f \circ \sigma|_{x_1=0} = f \circ \sigma_*$$

where $\sigma_* = \sigma|_{x_1=0}$.

From (2.8) and (2.9) we have

$$f \circ \sigma_* = w(x_1, \dots, x_n)|_{x_1=0}.$$

Thus $w|_{x_1=0}$ is H -sufficient in \mathbb{R}^{n-1} .

Since $w|_{x_1=0}$ is H -sufficient, by a well-known result, there exist $c > 0$ and a neighbourhood U of 0 in \mathbb{R}^{n-1} such that

$$d(\nabla_1 w(x'), \dots, \nabla_p w(x')) \geq c|x'|^{r-1} \geq c|x'|^{r+1}, \quad x' = (0, x_2, \dots, x_n).$$

On the other hand,

$$d(\nabla_1 w(x'), \dots, \nabla_p w(x)) = d(v_1^w, \dots, v_p^w)|_{x_1=0}.$$

Therefore, considering d in the hyperspace $x_1 = 0$, we have

$$d(v_1^w, \dots, v_p^w) \geq c|x'|^{r+1} \quad \forall x \in U.$$

Thus $a_{i1} \neq 0$ for every i .

Write the vectors λ_k^i , $k = 2, \dots, p$, in the form

$$\lambda_k^i = (\alpha_{k,1}^i, \alpha_{k,2}^i, \dots, \alpha_{k,n}^i).$$

Since

$$v_1^w(a_i) \in \text{Span}\{v_2^w(a_i) + \lambda_2^i, \dots, v_p^w(a_i) + \lambda_p^i\},$$

we have

$$\nabla_1 w(a_i) = \left(\frac{\partial w_1}{\partial x_1}(a_i), \dots, \frac{\partial w_1}{\partial x_n}(a_i) \right)$$

$$\in \text{Span} \left\{ \left(\frac{\partial w_1}{\partial x_1}(a_i) + \frac{\alpha_{2,1}^i}{a_{i1}}, \frac{\partial w_2}{\partial x_2}(a_i) + \alpha_{2,2}^i, \dots, \frac{\partial w_2}{\partial x_n}(a_i) + \alpha_{2,n}^i \right), \dots \right. \\ \left. \dots, \left(\frac{\partial w_p}{\partial x_1}(a_i) + \frac{\alpha_{p,1}^i}{a_{i1}}, \frac{\partial w_p}{\partial x_2}(a_i) + \alpha_{p,2}^i, \dots, \frac{\partial w_p}{\partial x_n}(a_i) + \alpha_{p,n}^i \right) \right\}.$$

Let us put

$$\lambda_2^i = \left(\frac{\alpha_{2,1}^i}{a_{i1}}, \alpha_{2,2}^i, \dots, \alpha_{2,n}^i \right), \\ \dots \dots \dots \\ \lambda_p^i = \left(\frac{\alpha_{p,1}^i}{a_{i1}}, \alpha_{p,2}^i, \dots, \alpha_{p,n}^i \right).$$

Then we have $|\lambda_k^i| = o(|a_i|^{r-1})$, $k = 2, \dots, p$.

In fact, since $|\lambda_k^i| = o(|a_i|^{r+1})$, $k = 2, \dots, p$ and

$$\lambda_k^i = (\alpha_{k,1}^i, \alpha_{k,2}^i, \dots, \alpha_{k,n}^i),$$

we get $|\alpha_{k,j}^i| = o(|a_i|^{r+1})$, $j = 1, 2, \dots, n$. On the other hand,

$$|\alpha_{k,1}^i| = |a_{i1}| \left| \frac{\alpha_{k,1}^i}{a_{i1}} \right| \quad \text{and} \quad |\alpha_{k,1}^i| = o(|a_i|^{r+1});$$

we get

$$(2.10) \quad |a_{i1}| \left| \frac{\alpha_{k,1}^i}{a_{i1}} \right| = o(|a_i|^{r+1}).$$

Since $|a_{i1}|/|a_i|^2 \leq |a_{i1}|/|a_{i1}|^2 = 1/|a_{i1}| \rightarrow \infty$, we have

$$\lim_{i \rightarrow \infty} \frac{|a_{i1}|}{|a_i|^2} = \infty.$$

Thus from (2.10) we obtain

$$\left| \frac{\alpha_{k,1}^i}{a_{i1}} \right| = o(|a_i|^{r-1}).$$

Since $|\alpha_{k,j}^i| = o(|a_i|^{r-1})$, we have $|\lambda_k^i| = o(|a_i|^{r-1})$, $k = 2, \dots, p$. Finally, we get

$$\text{grad } w_1(a_i) = \sum_{k=2}^p \alpha_k (\text{grad } w_k(a_i) + \lambda_k^i), \quad |\lambda_k^i| = o(|a_i|^{r-1}).$$

Repeating the proof of Theorem in [1], we conclude the proof of Theorem 2.

2.3. Proof of Theorem 3. Assume that $f: \mathbb{R}^n \rightarrow \mathbb{R}^p$, $f(0) = 0$ and $f'(f) = w$. Let us show that there exists a homeomorphism

$$\sigma: \mathbb{R}^n \rightarrow \mathbb{R}^n, \quad \sigma \{x \in \mathbb{R}^n: x_1 = 0\} \subset \{x \in \mathbb{R}^n: x_1 = 0\}$$

such that $f_0 \circ \sigma = w$.

where N_i is the projection of the vector $\Phi_i(F)$ onto the space spanned by $\Phi_j(F)$, $j \neq i$.

Note that $Y(x, t)$ is the projection of $(0, \dots, 0, 1)$ onto the subspace spanned by $\Phi_1(F), \dots, \Phi_p(F)$.

Thus

$$X_1(x, t) = (0, \dots, 0, 1) - Y(x, t)$$

is orthogonal to $\Phi_1(F), \dots, \Phi_p(F)$. Note that

$$\Phi_k(F) = \left(x_1 \frac{\partial F_k}{\partial x_1}, \dots, x_n \frac{\partial F_k}{\partial x_n}, \frac{\partial F_k}{\partial t} \right).$$

Thus if we put $X_1(x, t) = (X_{1,1}, \dots, X_{1,n}, X_{1,n+1})$, we have

$$x_1 \frac{\partial F_k}{\partial x_1} \cdot X_{1,1} + \dots + x_n \frac{\partial F_k}{\partial x_n} \cdot X_{1,n} + \frac{\partial F_k}{\partial t} \cdot X_{1,n+1} = 0$$

for $k = 1, \dots, p$. Let

$$X(x, t) = (x_1 X_{1,1}, x_2 X_{1,2}, \dots, x_n X_{1,n}, X_{1,n+1}).$$

Then $X(x, t)$ is orthogonal to ∇F_k , $k = 1, 2, \dots, p$.

From (3.6) and (3.2) it follows that

$$\lim_{x \rightarrow 0} |x|^{-1} Y(x, t) = 0.$$

Thus the vector $X_1(x, t)$ has properties (i), (ii), (iii) occurring in the proof of Theorem 1. It is easy to see that $X(x, t)$ has properties (i), (ii), (iii).

Repeating the last part of the proof of Theorem 1, we obtain the proof of Theorem 3.

References

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