# Shorouk Al-Issa, Ahmed Mohamed Ahmed El-Sayed <br> Positive integrable solutions for nonlinear integral and differential inclusions of fractional-orders 


#### Abstract

In this paper we study the global existence of positive integrable solution for the nonlinear integral inclusion of fractional order $$
x(t) \in p(t)+I^{\alpha} F_{1}\left(t, I^{\beta} f_{2}(t, x(\varphi(t)))\right), \quad t \in(0,1)
$$

As an application the global existence of the solution for the initial-value problem of the arbitrary (fractional) orders differential inclusion $$
\left.\frac{d x(t)}{d t} \in p(t)+I^{\alpha} F_{1}\left(t, D^{\gamma} x(t)\right)\right), \quad \text { a.e } t>0
$$ will be studied. 2000 Mathematics Subject Classification: 26A33, 34A12, 45G05. Key words and phrases: integral inclusion, fractional-calculus, Caratheodory condition, differential inclusion, fixed point theorem.


1. Introduction. The existence of integrable solution of the integral inclusion

$$
x(t) \in g(t)+I^{\alpha} F(t, x(\varphi(t)) \text { a.e on }(0,1), \alpha \in(0,1)
$$

where $F$ is lower semicontinuous from $R$ into $R$ and $F(.,$.$) is measurable, has been$ studied in [6].
Here we are concerned with the functional integral equation
(1) $\quad x(t)=p(t)+I^{\alpha} f_{1}\left(t, I^{\beta} f_{2}(t, x(\varphi(t)))\right.$ a.e on $(0,1), \alpha, \beta \in(0,1)$
and we prove the existence of a positive integrable solution of (1).
As a generalization of our results we study the existence of positive integrable solution of the nonlinear functional integral inclusion

$$
\begin{equation*}
x(t) \in p(t)+I^{\alpha} F_{1}\left(t, I^{\beta} f_{2}(t, x(\varphi(t))) \text { a.e on }(0,1), \alpha, \beta \in(0,1)\right. \tag{2}
\end{equation*}
$$

where the set-valued map $F(t,$.$) is lower semicontinuous from R^{+}$into $R^{+}$and $F(.,$.$) is measurable.$
Finally, we prove the existence of a nondecreasing solution $x \in L^{1}$ of the initial value problem of the differential inclusion of arbitrary (fractional) orders

$$
\begin{equation*}
\left.\frac{d x(t)}{d t} \in p(t)+I^{\alpha} F_{1}\left(t, D^{\gamma} x(t)\right)\right), \quad \text { a.e } t>0 \tag{3}
\end{equation*}
$$

with the initial data

$$
\begin{equation*}
x(0)=x_{\circ} . \tag{4}
\end{equation*}
$$

2. Preliminaries. Let $L^{1}=L^{1}(I)$ be the class of Lebesgue integrable functions on the interval $I=[a, b], 0 \leqslant a<b<\infty$ and let $\Gamma($.$) be the gamma function.$

Definition 2.1 The fractional integral of the function $f(.) \in L^{1}(I)$. of order $\alpha \in R^{+}$is defined by (cf. [7], [8], [9] and [11])

$$
I_{a}^{\alpha} f(t)=\int_{a}^{t} \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} f(s) d s
$$

Definition 2.2 The (Caputo) fractional order derivative $D^{\alpha}, \alpha \in(0,1]$ of the absolutely continuous function $g$ is defined as (see [2], [8], [9] and [11] )

$$
D_{a}^{\alpha} g(t)=I_{a}^{1-\alpha} \frac{d}{d t} g(t), \quad t \in[a, b] .
$$

The following two theorems will be needed in the proof of our main result.
Theorem 2.3 (Nonlinear Alternative of Leray-Shauder type [4]) Let $U$ be an open subset of a convex set $D$ in a Banach space $X$. Assume $0 \in U$ and $T \in C(\bar{U}, D)$. Then either
$\left(\mathrm{A}_{1}\right) T$ has a fixed point in $\bar{U}$ or
$\left(\mathrm{A}_{1}\right)$ there exists $\gamma \in(0,1)$ and $x \in \partial U$ such that $x=\gamma T x$.

Theorem 2.4 (Kolmogorov Compactness Criterion [5]) Let $\Omega \subseteq L^{p}(0,1), 1 \leqslant$ $p \leqslant \infty$. If
(i) $\Omega$ is bounded in $L^{p}(0,1)$ and
(ii) $x_{h} \rightarrow x$ as $h \rightarrow 0$ uniformly with respect to $x \in \Omega$, then $\Omega$ is relatively compact in $L^{p}(0,1)$, where

$$
x_{h}(t)=\frac{1}{h} \int_{0}^{t+h} x(s) d s
$$

3. Main results. In this section we present our main result by proving the existence of positive solution $x \in L^{1}$ for the functional integral equation (1). To facilitate our discussion, let us first state the following assumption:
(i) $p \in L^{1}$.
(ii) $f_{i}:(0,1) \times R^{+} \rightarrow R^{+}, i=1,2$ satisfy Caratheodory condition i.e $f_{i}$ are measurable in $t$ for any $x \in R^{+}$and continuous in $x$ for almost all $t \in(0,1)$. There exists two function $a_{i}(.) \in L^{1}$ and two positive constant $b_{i}$ such that

$$
\left|f_{i}(t, x)\right| \leqslant a_{i}(t)+b_{i}|x|, \quad i=1,2 \quad \forall t \in(0,1) \text { and } x \in R .
$$

(iii) $\phi:(0,1) \rightarrow(0,1)$ is absolutely continuous, and there exists a constant $M>0$ such that $\varphi^{\prime}(t) \geqslant M, \quad \forall t \in(0,1)$.
(iv) Assume that every solution $x(.) \in L^{1}$ to the equation

$$
x(t)=\gamma\left(p(t)+\int_{0}^{t} \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} f_{1}\left(s, \int_{0}^{s} \frac{(s-\tau)^{\beta-1}}{\Gamma(\beta)} f_{2}(\tau, x(\varphi(\tau))) d \tau\right) d s\right)
$$

$t \in(0,1), \quad 0<\beta<1, \quad \gamma \in(0,1)$, satisfies $\|x\| \neq r(r>0$ is arbitrary but fixed).

Define the operator $T$
$T x(t)=p(t)+\int_{0}^{t} \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} f_{1}\left(s, \int_{0}^{s} \frac{(s-\tau)^{\beta-1}}{\Gamma(\beta)} f_{2}(\tau, x(\varphi(\tau))) d \tau\right) d s, \quad t \in[0,1]$,

Now, we are in position to formulate and prove our main result.

Theorem 3.1 Let the assumptions (i)-(iv) are satisfied. Then equation (1) has at least one positive solution $x \in L_{1}$

Proof Let $x$ be an arbitrary element in the open set $B_{r}=\{x:\|x\|<r, r>0\}$.

Then from assumptions (1) and (2) we have,

$$
\begin{aligned}
& \|T x\|=\int_{0}^{1}|(T x)(t)| d t \leqslant \int_{0}^{1}|p(t)| d t \\
& +\int_{0}^{1} \int_{0}^{t} \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)}\left|f_{1}\left(s, \int_{0}^{s} \frac{(s-\tau)^{\beta-1}}{\Gamma(\beta)} f_{2}(\tau, x(\varphi(\tau))) d \tau\right)\right| d s d t \\
& \leqslant \int_{0}^{1}|p(t)| d t+\int_{0}^{1} \int_{0}^{t} \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} a_{1}(s) d s d t \\
& \left.+b_{1} \int_{0}^{1} \int_{0}^{t} \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} \int_{0}^{s} \frac{(s-\tau)^{\beta-1}}{\Gamma(\beta)}\left|f_{2}(\tau, x(\varphi(\tau)))\right| d \tau\right) d s d t \\
& \leqslant\|p\|+\int_{0}^{1}\left|a_{1}(s)\right| \int_{s}^{1} \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} d t d s \\
& +b_{1} \int_{0}^{1} \int_{0}^{t} \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} \int_{0}^{s} \frac{(s-\tau)^{\beta-1}}{\Gamma(\beta)} a_{2}(\tau) d \tau d s d t \\
& +b_{1} b_{2} \int_{0}^{1} \int_{0}^{t} \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} \int_{0}^{s} \frac{(s-\tau)^{\beta-1}}{\Gamma(\beta)}|x(\varphi(\tau))| d \tau d s d t \\
& \leqslant\|p\|+\int_{0}^{1}\left|a_{1}(s)\right| \frac{t^{\alpha}}{\Gamma(\alpha+1)} d s+b_{1} \int_{0}^{1} I^{\alpha+\beta} a_{2}(t) d t \\
& +b_{1} b_{2} \int_{0}^{1} I^{\alpha+\beta}|x(\varphi(t))| d t \\
& \leqslant\|p\|+\int_{0}^{1}\left|a_{1}(s)\right| \frac{t^{\alpha}}{\Gamma(\alpha+1)} d s+b_{1} \int_{0}^{1} \int_{0}^{t} \frac{(t-s)^{\alpha+\beta-1}}{\Gamma(\alpha+\beta)}\left|a_{2}(s)\right| d s d t \\
& +b_{1} b_{2} \int_{0}^{1} \int_{0}^{t} \frac{(t-s)^{\alpha+\beta-1}}{\Gamma(\alpha+\beta)}|x(\varphi(s))| d s d t \\
& \leqslant\|p\|+\frac{\left\|a_{1}\right\|}{\Gamma(\alpha+1)}+b_{1} \int_{0}^{1}\left|a_{2}(s)\right| \int_{s}^{1} \frac{(t-s)^{\alpha+\beta-1}}{\Gamma(\alpha+\beta)} d t d s \\
& +b_{1} b_{2} \int_{0}^{1}|x(\varphi(s))| \int_{s}^{1} \frac{(t-s)^{\alpha+\beta-1}}{\Gamma(\alpha+\beta)} d t d s \\
& \leqslant\|p\|+\frac{\left\|a_{1}\right\|}{\Gamma(\alpha+1)}+b_{1} \int_{0}^{1}\left|a_{2}(s)\right| \frac{t^{\alpha+\beta}}{\Gamma(\alpha+\beta+1)} d s \\
& +b_{1} b_{2} \int_{0}^{1}|x(\varphi(s))| \frac{t^{\alpha+\beta}}{\Gamma(\alpha+\beta+1)} d s \\
& \leqslant\|p\|+\frac{\left\|a_{1}\right\|}{\Gamma(\alpha+1)}+b_{1} \frac{\left\|a_{2}\right\|}{\Gamma(\alpha+\beta+1)}+\frac{b_{1} b_{2}}{M \Gamma(\alpha+\beta+1)} \int_{0}^{1}|x(\varphi(s))| \varphi^{\prime}(s) d s \\
& \leqslant\|p\|+\frac{\left\|a_{1}\right\|}{\Gamma(\alpha+1)}+\frac{b_{1}\left\|a_{2}\right\|}{\Gamma(\alpha+\beta+1)}+\frac{b_{1} b_{2}}{M \Gamma(\alpha+\beta+1)} \int_{\varphi(0)}^{\varphi(1)}|x(\varphi(u))| d u \\
& \leqslant\|p\|+\frac{\left\|a_{1}\right\|}{\Gamma(\alpha+1)}+\frac{b_{1}\left\|a_{2}\right\|}{\Gamma(\alpha+\beta+1)}+\frac{b_{1} b_{2}}{M \Gamma(\alpha+\beta+1)} \int_{0}^{1}|x(u)| d u \\
& \leqslant\|p\|+\frac{\left\|a_{1}\right\|}{\Gamma(\alpha+1)}+\frac{b_{1}\left\|a_{2}\right\|}{\Gamma(\alpha+\beta+1)}+\frac{b_{1} b_{2}\|x\|}{M \Gamma(\alpha+\beta+1)} \text {. }
\end{aligned}
$$

Hence the above inequality means that the operator $T$ maps $B_{r}$ into $L^{1}$.

Now, we will show that $T$ is compact. To achieve this goal we will apply Theorem 2.4. So, let $\Omega$ be a subset of $B_{r}$. Then $T(\Omega)$ is bounded in $L^{1}$ i.e condition (i) of Theorem 2.4 is satisfied.
It remains to show that $(T x)_{h} \rightarrow T x$ in $L^{1}$ as $h \rightarrow 0$ uniformly with respect to $T x \in \Omega$. We have the following :

$$
\begin{aligned}
&\left\|(T x)_{h}-(T x)\right\|= \int_{0}^{1}\left|(T x)_{h}(t)-(T x)(t)\right| d t \\
&= \int_{0}^{1}\left|\frac{1}{h} \int_{t}^{t+h}(T x)_{h}(\tau) d \tau-(T x)(t)\right| d t \\
&= \int_{0}^{1}\left|\frac{1}{h} \int_{t}^{t+h}\left((T x)_{h}(\tau)-(T x)(t)\right) d \tau\right| d t \\
& \leqslant \int_{0}^{1}\left(\frac{1}{h} \int_{t}^{t+h}|p(\tau)-p(t)| d \tau d t\right. \\
& \left.+\int_{0}^{1} \frac{1}{h} \int_{t}^{t+h} \right\rvert\, I^{\alpha} f_{1}\left(\tau, I^{\beta} f_{2}(\tau, x(\varphi(\tau)))\right. \\
& \quad-I^{\alpha} f_{1}\left(t, I^{\beta} f_{2}(t, x(\varphi(t))) \mid d \tau d t\right.
\end{aligned}
$$

Now $f_{1}, f_{2} \in L^{1}$ and $I^{\alpha} f_{1}, I^{\beta} f_{2} \in L^{1}$, then (cf. [12] )

$$
\left.\frac{1}{h} \int_{t}^{t+h} \right\rvert\, I^{\alpha} f_{1}\left(\tau, I^{\beta} f_{2}(\tau, x(\varphi(\tau)))-I^{\alpha} f_{1}\left(t, I^{\beta} f_{2}(t, x(\varphi(t))) \mid d \tau d t \rightarrow 0\right.\right.
$$

Moreover $p(.) \in L^{1}$. So, we have

$$
\frac{1}{h} \int_{t}^{t+h}|p(\tau)-p(t)| d \tau \rightarrow 0
$$

for a.e $t \in L^{1}$. Therefore, by Theorem 2.4 we have that $T(\Omega)$ is relatively compact, that is, $T$ is compact operator.
Set $U=B_{r}$ and $D=X=L^{1}[0,1]$. Then in the view of assumption (4) condition $\left(A_{2}\right)$ of Theorem 2.3 does not hold. Theorem 2.3, implies that $T$ has a fixed point. This completes the proof.
4. Functional integral inclusion. Consider now the integral inclusion (2), where $F_{1}:(0,1) \times R^{+} \rightarrow 2^{R^{+}}$has nonempty closed convex values.
As an important consequence of the main result we can present the following:

ThEOREM 4.1 Let the assumptions of Theorem 3.1 are satisfied and the multifunction $F_{1}$ satisfies the following assumptions:
(1) $F_{1}(t, x)$ are non empty, closed and convex for all $(t, x) \in[0,1] \times R^{+}$,
(2) $F_{1}(t,$.$) is lower semicontinuous from R^{+}$into $R^{+}$,
(3) $F_{1}(.,$.$) is measurable,$
(4) There exists a function $a_{1} \in L^{1}$ and a positive number $b_{1}$ such that

$$
\left|F_{1}(t, x)\right| \leqslant a_{1}(t)+b_{1}|x| \quad \forall \quad t \in(0,1),
$$

Then there exists at least one positive solution $x \in L^{1}$ of the integral inclusion (2)
Proof By conditions (1)-(4) (see [1], [3], [6] [10] ) we can find a selection function $f_{1}$ (Caratheodory function) $f_{1}:(0,1) \times R^{+} \rightarrow R^{+}$such that $f_{1}(t, x) \in F_{1}(t, x)$ for all $(t, x) \in(0,1) \times R^{+}$, this function satisfies condition (ii) of Theorem 3.1.
Clearly all assumptions of Theorem 3.1 are hold, then there exists a positive solution $x \in L^{1}$ such that

$$
x(t)-p(t)=I^{\alpha} f_{1}\left(t, I^{\beta} f_{2}(t, x(\varphi(t)))\right) \in I^{\alpha} F_{1}\left(t, I^{\beta} f_{2}(t, x(\varphi(t)))\right)
$$

5. Differential inclusion. Consider now the initial value problem of the differential inclusion (3) with the initial data (4)

THEOREM 5.1 Let the assumption of Theorem 4.1 are satisfied, then the initial value problem (3)-(4) has at least one positive nondecreasing solution $x \in L^{1}$.

Proof Let $y(t)=\frac{d x(t)}{d t}$, then equation (3) is transformed to the integral inclusion

$$
\begin{equation*}
y(t) \in p(t)+I^{\alpha} F_{1}\left(s, I^{1-\gamma} y(s)\right) . \tag{6}
\end{equation*}
$$

Let $\phi(t)=t, f_{2}(t, x)=x$ and $\beta=1-\gamma$, then by Theorem 4.1 the integral inclusion (6) has at least one positive solution $y \in L^{1}$.
This implies that the existence of the absolutely continuous solution

$$
x(t)=x_{\circ}+\int_{0}^{t} y(s) d s
$$

of the initial-value problem (3)-(4), and this solution is positive and non decreasing.

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